

SEE IT BEFORE IT HAPPENS

# GEARLESS MOTOROLLER AND PALLET CONVEYOR

# GEARLESS MOTOROLLER AND PALLET CONVEYOR

Introducing the future in sorting and material handling technology





Complete technological innovation in movement

**Motor Power Company** keeps developing new concepts in sorting and material handling.

Our goal is sharing with the market our domain expertise in intralogistics; innovative solutions through our gearless and geared technology products. We propose motion control bundles composed by gearless motorollers and smart drives

All our solutions are in-house developed and are particularly oriented for control, movement, storage and protection of materials and products throughout manufacturing, sorting, warehousing, distribution, consumption and disposal. **Motor Power Company** specialises in the design, development and manufacturing of high performance industrial motion solutions. We have acquired consolidated expertise and technical know-how from 30 years experience with all kinds of applications and through our continuous commitment to research and development.

This allows us to partner leading international companies in the supply of products and solutions for automation and motion control.





# GEARLESS MOTOROLLERS AND DRIVES

# Increased efficiency and limitless performances

**Motor Power Company** introduces these perfect matched bundles costituted by gearless motorollers and smart drives. Everything has been conceived as a specific product for conveyor, crossbelt or any roller transfer systems.

Two versions are proposed; frameless cartridges without tube, to be inserted into the roller to be moved, and power pack version, a ready to use motoroller embedded in its own tube. The technology on which the motor is based comes from the direct drive torque motors. Consequently, the motion is transmitted directly from the motoroller to the load, without any gears.

# Motoroller without gears ensures:

#### > HIGH MTBF

as the motoroller needs less components than the standard kinematic chain

#### > SYSTEM EFFICIENCY INCREASE

due to the absence of gears inside the motoroller

### > ACCURACY

due to the feedback reliability

#### > HIGH DYNAMIC

thanks to the direct drive technology

#### > EASY REPLACEMENT

with the autotuning system of DMR Drives, the substitution

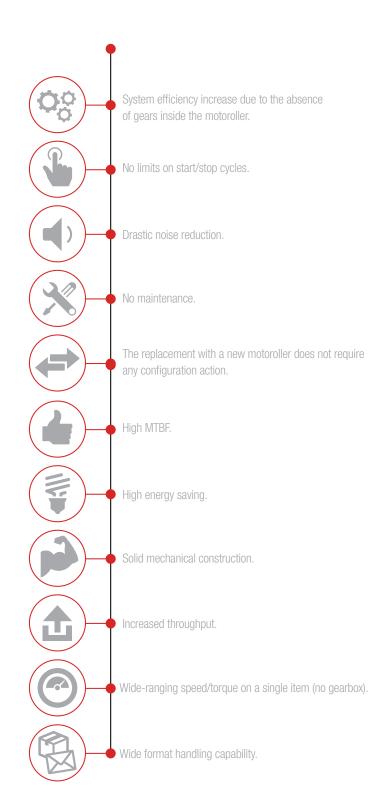
with a new motoroller does not require any configuration action

#### > EASY COMMISSIONING

due to a unique part number, there are no different gearbox ratios to handle according to different speed needs

### > WIDE SPEED AVAILABILITY

one motoller for all speed range





# THE GEARLESS MOTOROLLER SERIES AT A GLANCE

## **GEARLESS MOTOROLLER 46 Cartridge version**

### 800rpm@24-48 Vdc

Frameless gearless cartridge motoroller for general conveyor applications.

Suitable for 50mm roller tube integration, roller tube range available on request

#### **Features**

- » Two models
- » Rated power 50 Watt and 115 Watt
- » Rated torque 0,6 Nm and 1,35 Nm
- Hall sensors and encoder feebackfor higher precision
- » Cartridge diameter 46 mm suitable for all 50 mm diameter tube
- » 24 and 48Vdc power supply
- » Full speed control
- » Wide roller customization

# **GEARLESS POWER PACK MOTOROLLER 60**

#### 800rpm@60 Vdc



Tube equipped gearless motoroller for cross belt driving and controlling

#### **Features**

- » Ready to use
- » Rated power 235 Watt
- » Rated torque 2,8 Nm
- » 60Vdc power supply
- » 48 and 65 Vdc for power supply
- » Full speed control

# **GEARLESS MOTOROLLER 76 Cartridge version**

#### 800rpm@48-65 Vdc



#### **Features**

- » Rated power 260 WattZ
- » Rated torque 3,1 Nm
- » Encoder feeback for higher precision
- » Cartridge diameter 76 mm suitable for alla 80 mm diameter tube
- » 48 and 65 Vdc for power supply
- » Full speed control
- » Wide roller customization



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# THE DRIVE SERIES AT A GLANCE

# DMR 50-5/50 DUAL AXES DRIVE



The perfect matched drive for enhancing motoroller 46 features

#### **Features**

- » Dual axes operation
- » 24 and 48 Vdc operating supply voltage
- » Encoder and Hall Sensor feeback
- » CanOpen Fieldbus
- » RS485 programming interface
- » I/O programmability for speed, start and stop control

# LITE PRO DRIVE



Lite Pro drive is ideal for controlling motoroller 60

#### **Features**

- »24 and 48 Vdc operating supply voltage
- » Encoder and Hall Sensor feeback
- » CanOpen Fieldbus
- » I/O programmability for speed, start and stop control

# DMR 76-10/65



Motoroller 76 matches drive DMR 76-10/65 for the perfect bundle

#### **Features**

- » 24 and 65 Vdc operating supply voltage
- » Encoder and Hall Sensor feeback
- » Profibus Fieldbus
- » I/O programmability for speed, start and stop control
- » I/O proxy dual loop



# **MTR 46 AD**

# Gearless motorized driven roller featuring integrated drive





**Most powerful motorized driven** roller on the market



Direct drive technology offers superior energy saving compared to conventional technology



48 VDC power supply



**One model runs** any speed and torque



The elimination of gears results in an **extremely quiet motor roller** 



**Standard 5 pins - M8 - connector** for ease of use



**Encoder Feedback** provides precise speed control, with 7168 pulses per revolution.

Based on 15 years of expertise in gearless motorized roller technology, the MTR 46 AD takes performance to the next level. Developed from the proven MTR 46 series, this new version enhances the already remarkable benefits of direct drive technology by integrating an advanced electronic drive.

MTR 46 AD series revolutionized energy efficiency with its gearless design and superior energy savings compared to traditional geared systems. Its direct drive motor optimizes performance and also ensures remarkably quiet operation, making it ideal for noise-sensitive environments. With its ability to cover any speed and torque with a single model, MTR 46 AD simplifies design and reduces inventory needs. Now, with the MTR 46 AD, we take this innovation even further. The integrated drive enhances control, efficiency, and ease of installation, making this motorized roller the perfect choice for seamless automation.

Experience the future of motion technology-streamlined, powerful, and intelligently designed.

# Application advantages

Our advanced direct drive technology eliminates the constraints of gearbox ratios, enabling simple torque and speed variations with just one motorized roller model for any conveying application. This innovation simplifies inventory and design while enhancing performance and energy efficiency-key factors for material handling industries striving for optimization and sustainability.



# **MTR 46 AD**

# Power, efficiency and innovative design



MTR 46 AD is today the most powerful motorized driven roller on the market, delivering 75W power ratings, enabling faster movement and higher payload capacity. Its advanced gearless direct drive design minimizes mechanical losses, reduces energy costs, and ensures quiet operation. The 48Vdc power supply enhances efficiency and simplifies wiring.

# **Advanced Control and Connectivity**

MTR 46 AD features an encoder with 7168 pulses per revolution for precise speed control.

It supports two interface options: Analog Velocity and CANopen, compatible with DS301/DS402 protocols for Industry 4.0 integration. A standard 5 pin - M8 connector ensures easy connection to automation systems.

# Flexible and easy integration

With its gearless design, a single model meets various application needs, simplifying inventory management and maintenance.

The integrated drive reduces wiring and streamline installation. It is available in two versions: a frameless 46 mm cartridge (for 50mm rollers) and a Power Pack solution with a complete 50mm roller.

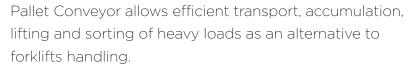
#### **Technical data**

SPECIFICATION	MTR 46.105	
STALL TORQUE	1.05 Nm	
PEAK TORQUE	3.2 Nm	
RATED SPEED	800 RPM (2 m/s)	
RATED POWER	75W @ 48Vdc	
POWER SUPPLY	24 and 48 Volt	
VERSIONS	Cartridge (46mm), Complete Roller (50mm)	





# Geared solution for driving pallet conveyor application



In warehouse automation operations a pallet conveyor is generally utilized to move loads of several hundreds kilograms while ensuring continuous feed of work and cutting edge efficiency.

The high-performance synchronous brushless servomotor, coupled with planetary gearbox, ensures performance with loads up to 1500 kg per zone.



- > HIGH DYNAMICS
- > EASY CONVEYOR DESIGN
- > THE REPLACEMENT WITH A NEW MOTOROLLER

  DOES NOT REQUIRE ANY CONFIGURATION ACTION
- > HIGH MTBF
- > HIGH ENERGY SAVING

c**™**us (€



# PALLET CONVEYOR MOTOROLLER

# **POWER PACK MOTOROLLER 70**



MOTOROLLER geared solution for driving pallet conveyor application

#### **Features**

- » Ready to use pallet conveyor motoroller
- » Rated power 265 Watt
- » Planetary gear box ratio 1:35
- » Tube diameter 70mm
- » Conveyor velocity 22,2 m/min (0,37 m/sec)
- » Load up to 1500 Kg
- » Supply voltage available: 48 Vdc, 230 Vac, 400 Vac

# **POWER PACK MOTOROLLER 89**



MOTOROLLER geared solution for driving pallet conveyor application

#### **Features**

- » Ready to use pallet conveyor motoroller
- » Rated power 400 Watt
- » Planetary gear box ratio 1:45
- » Tube diameter 89mm
- » Conveyor velocity 16,2 m/min (0,27 m/sec)
- » Load up to 1500 Kg
- » Supply voltage available: 48 Vdc, 230 Vac, 400 Vac

# DRIVE DMR PC 6/50



DMR PC 6/50 drive allows for the perfect match with the Pallet Conveyor Motoroller 70 and 89, ensuring optimal bundling performance

#### **Features**

- » Dual axes operation
- » 48 Vdc operating supply voltage
- » Nominal current 6 A
- » Peak current 15 A
- » Ethercat, Profinet and Ethernet IP Fieldbus
- » 3 photoeyes inputs
- » Digital I/O



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# >>> DISCOVER OUR PRODUCT RANGE

# MOTOROLLER FRAMELESS - GEARLESS CARTRIDGE ONLY

MTR FL 46 140 13 H1 D0 XXX

Model Size Winding Feedback Connection Optional



1 Model MTR FL 46 MTR FL 76

2 Size MTR FL 46 140 MTR FL 76 100

Winding MTR FL 46 13 MTR FL 76 14

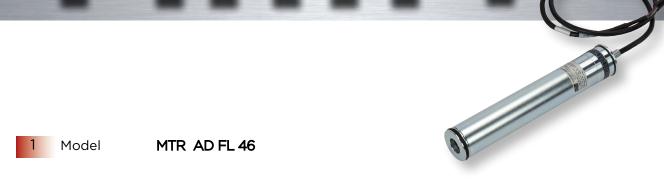
4 Feedback **H1** Hall Sensor **E1** Incremental encoder ABZ - 3584 cpr

5 Connection **DO** - cable output with connectors

# MOTOROLLER FRAMELESS - GEARLESS CARTRIDGE ONLY

MTR AD FL 46 105 29 E2 D3 A XXX

Model Size Winding Feedback Connection Fieldbus Optional



2 Size **MTR AD FL 46** 105

Winding MTR AD FL 46 29

4 Feedback **E2** Incremental encoder 7168 ppr

5 Connection **D3** - cable output with connectors

6 Fieldbus A - Digital I/O C - CanOpen

# MOTOROLLER POWER PACK - GEARLESS MOTOROLLER WITH TUBE

MTR PP 76	100	14	H1	DO	01	-	80	-	XXX
Model	Size	Winding	Feedback	Connection	Fixed shaft	Tube type	Tube lenght	Indle shaft	Optional
1	2	3	4	5	6	7	8	9	10

1 Model MTR PP 46

MTR AD PP 46 MTR PP 60 MTR PP 76

2 Size **MTR PP 46** 140

MTR AD PP 46 105 MTR PP 60 150 MTR PP 76 100

Winding MTR PP 46 13

MTR AD PP 46 29 MTR PP 60 21 MTR PP 76 14

4 Feedback **H1** Hall Sensor

E1 Incremental encoder ABZ

5 Connection **DO** - cable output with connectors

6 Fixed shaft 01 - Male tread

Tube type<sup>(\*)</sup> **01 -** Standard tube **02 -** Double grooved tube

**04 -** Poly-V pulley tube (\*\*) **05 -** Double grooved pulley tube **06 -** Tapered sleeves tube

**07 -** Double grooved and tapered sleeves tube **08 -** Poly-V and tapered sleeves tube (\*\*)

09 - Double grooved pulley and tapered sleeves tube

(\*) for MTR PP 46 only  $\,\,^{(*)}$  This version is not available for sale in Germany

Tube lenght in mm<sup>(\*)</sup> Referral "R" on drawings

(\*) For MTR PP 60 lenght is fixed

9 Indle shaft<sup>(\*)</sup> AA: hex spring loaded

AB: female thread

AC: poly-V hex spring loaded

AD: poly-V thread

(\*) for MTR PP 46 only



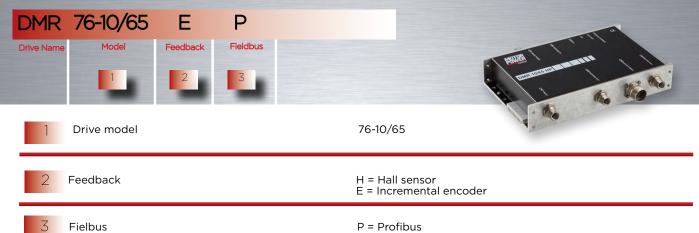
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# DMR 50-5/50 DRIVE TYPE



4 Input Logic 0 = PNP input 1 = NPN input

# **DMR 76-10/65 DRIVE TYPE**



# LITE PRO DRIVE TYPE

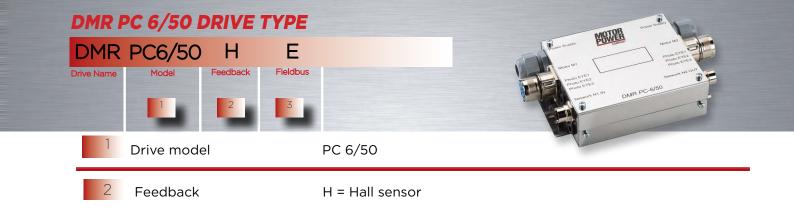
	TO DRI	VE I IP		
LPRO	Е	40	С	
Drive Name	Feedback	Model	Fielbus	
	1	2	3	
1	Feedback			E = Hall sensor and encoder
2	Model (out	put current	z) Arms	40 = 8/24
3	Fielbus			C = CANopen

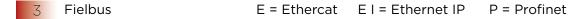
SEE IT BEFORE IT HAPPENS



# **PALLET CONVEYOR MOTOROLLER POWER PACK**

MTR PP 89 04 Model Siz	
1 2	9 10
1 Model	MTR PP 70 MTR PP 89
2 Size	MTR PP 70 045 MTR PP 89 045
3 Winding	MTR PP 70 01 - 04 MTR PP 89 04
4 Feedback	<b>H1</b> Hall Sensor
5 Connection	DO = cable output with M15 connectors D1 = cable output with M23 connectors D2 = cable output with Harting A0 = cable output with free wires
6 Fixed shaft	<b>01 -</b> Male tread
7 Tube type	<b>01 -</b> Standard tube
8 Tube	lenght in mm See drawings reference "R" letter
9 Indle shaft	AA: hex spring loaded AB: female thread
10 Optional	<b>02</b> brake







# **MOTOROLLER 46 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified Continuous F Totally enclosed. Self-cooled NTC AMBIENT TEMPERATURE 0 to 40 °C
AMBIENT HUMIDITY 5 to 85% (r
POLES 28
UL RECOGNIZED CURUS E46

O to 40 °C 5 to 85% (non-condensing) 28 cURus E468964

#### Motoroller 46 140 13

Stall torque	Cn0	Nm	1,5
Peak torque	Cpk	Nm	4,5
Rated torque	Cn	Nm	1,35
Rated working speed	nM	rpm	800
Rated voltage	Un	Vdc	48
Maximum working speed @ 24Vdc	nmax	rpm	500
Maximum working speed @ 48Vdc	nmax	rpm	1000
Rated output power	Pn	W	115
Stall current	InO	Arms	3,3
Peak current	lpk	Arms	10,61
Rated current	In	Arms	3
Torque constant	Kt	Nm/Arms	0,45
Voltage constant	Ke	Vrsm/ Krpm	27,6
Phase/phase resistance @25°C	Rff	Ohm	1,23
Phase/phase inductance	Lff	mH	2,81
Electrical time constant	Te	ms	2,3
Rotor inertia	Jm	Kg cm²	6,1
Motor weight	m	Kg	2,73
Axial shaft load @800 rpm	Fa	Ν	
Radial shaft load @800 rpm	Fr	N	



# **MOTOROLLER 46 AD RATINGS AND SPECIFICATIONS**

TIME RATING
INSULATION CLASS
ENCLOSURE
THERMAL PROTECTION
CE certified

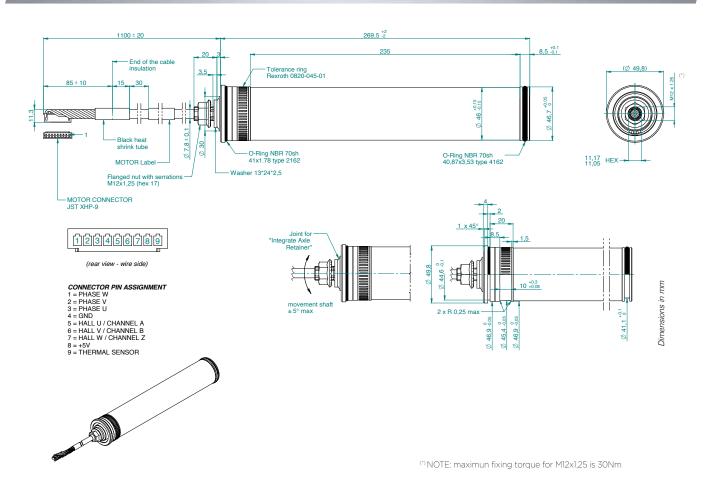
Continuous F Totally enclosed. Self-cooled NTC AMBIENT TEMPERATURE AMBIENT HUMIDITY 5 to 85% (non-condensing)
POLES 28
INSULATION SYSTEM UL /CSA cURus, DV155J File nr.:E216686

			Motoroller 46 AD 105 29
Stall torque	Cn0	Nm	1,0
Peak torque	Cpk	Nm	2,2
Rated torque	Cn	Nm	0,9
Rated working speed	nM	rpm	380
Rated voltage	Un	Vdc	48
Maximum working speed @ 24Vdc	nmax	rpm	1000
Maximum working speed @ 48Vdc	nmax	rpm	1150
Rated output power	Pn	W	35
Stall current	InO	Arms	1,47 - 2,09
Peak current	Ipk	Arms	3,45 - 4,87
Rated current	In	Arms	1,37 - 1,93
Torque constant	Kt	Nm/Arms	0,68
Voltage constant	Ke	Vrsm/ Krpm	41,0
Phase/phase resistance @25°C	Rff	Ohm	3,85
Phase/phase inductance	Lff	mH	8,20
Electrical time constant	Te	ms	2,13
Rotor inertia	Jm	Kg cm²	4,7
Motor weight	m	Kg	4,4
Axial shaft load @800 rpm	Fa	Ν	110
Radial shaft load @800 rpm	Fr	Ν	220 (applied on the rotor's centering)
DRIVE DATA			
Rated output power		W	50
Efficiency at rated power		%	> 95 %
Operative supply voltage		V	24 ÷ 60
Max voltage		V	80
Rated output current		Arms	2.0
Peak output current (peak time)		Arms (s)	11.0 (3)
Working temperature		°C	-30 ÷ 100



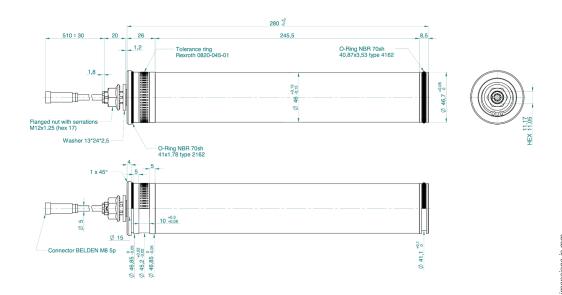
# **MOTOROLLER 46 FRAMELESS DIMENSIONS**

# Motoroller 46 140



# **MOTOROLLER 46 AD FRAMELESS DIMENSIONS**

# Motoroller 46 AD 105



FIELBUS A - DIGITAL I/O
CONNECTOR BELDEN M8 5p

Pin	Cable wire color	Function
1	Brown	MOT+
2	White	DIR
3	Blue	MOT-
4	Black	ERROR
5	Grey	SPEED

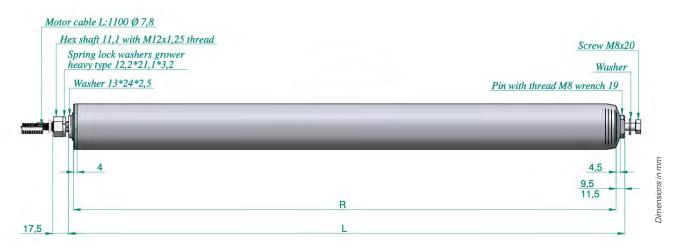
FIELBUS C - CanOpen

CONNECTOR BELDEN M8 5p

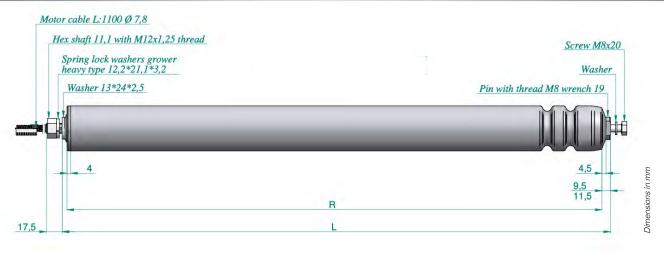
Pin	Cable wire color	Function
1	Brown	Power Supply (+)
2	White	CAN high
3	Blue	Ground GND (-)
4	Black	CAN low
5	Grey	to be def

# **MOTOROLLER 46 AND 46 AD POWER PACK TUBE TYPE**

# Motoroller 46/46 AD standard tube 01



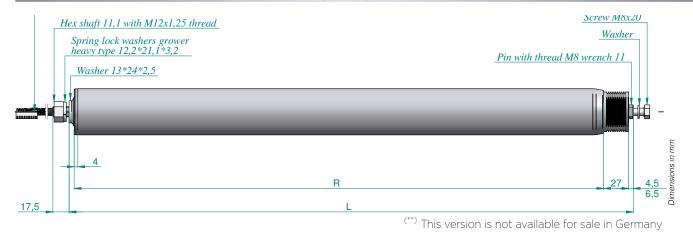
# Motoroller 46/46 AD double grooved tube 02



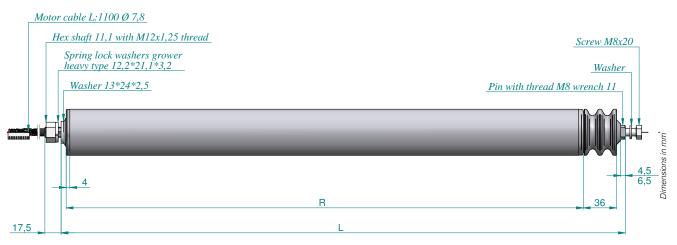


# **MOTOROLLER 46 AND 46 AD POWER PACK TUBE TYPE**

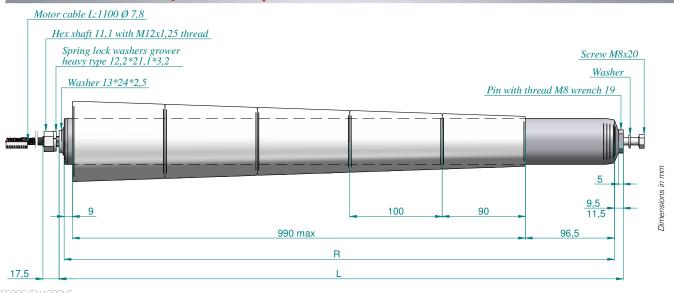
# Motoroller 46/46 AD poly-V pulley tube 04 "



# Motoroller 46/46 AD double grooved pulley tube 05



# Motoroller 46/46 AD tapered sleeves tube 06

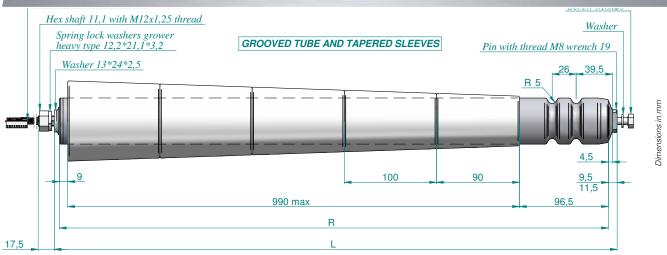




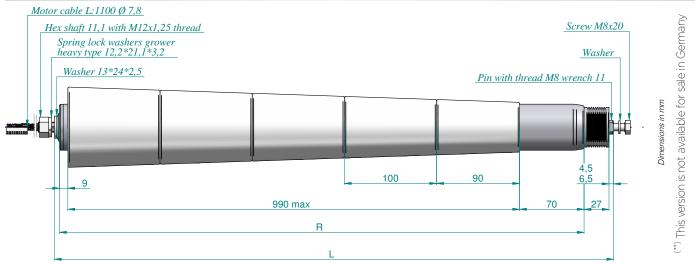
22

# **MOTOROLLER 46 AND 46 AD POWER PACK TUBE VERSIONS**

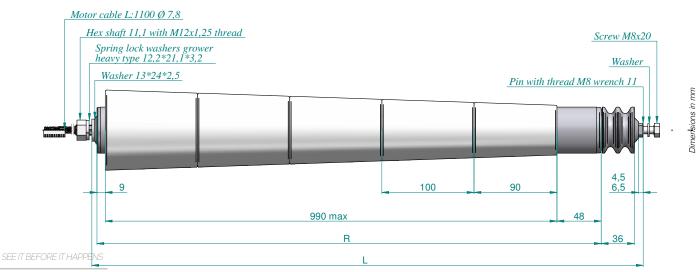
# Motoroller 46/46 AD double grooved and tapered sleeves tube 07



# Motoroller 46/46 AD poly-V pulley and tapered sleeves tube 08

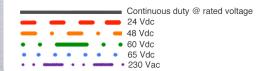


# Motoroller 46/46 AD double grooved pulley and tapered sleeves tube 09





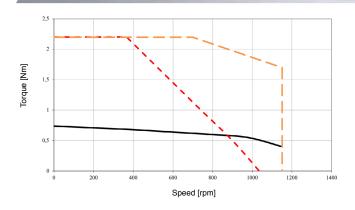
# **MOTOROLLER 46 TORQUE /SPEED CHARTS**

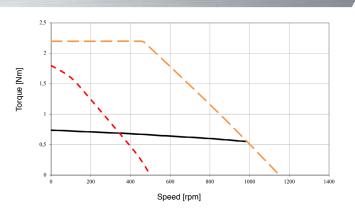




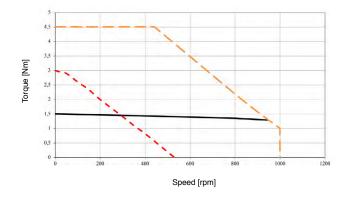
# **MOTOROLLER 46 75 06**

# **MOTOROLLER 46 75 13**





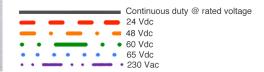
# **MOTOROLLER 46 140 13**





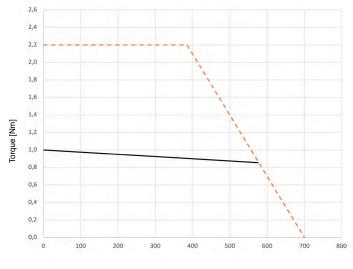
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# **MOTOROLLER 46 AD TORQUE /SPEED CHARTS**





# **MOTOROLLER 46 AD 105**



Speed [rpm]

SEE IT BEFORE IT HAPPENS

# **MOTOROLLER 60 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified

Continuous Totally enclosed. Self-cooled NTC

AMBIENT TEMPERATURE 0 to 40 °C
AMBIENT HUMIDITY 5 to 85% (non-condensing)
POLES 28
UL RECOGNIZED 28
CURUS E468964

			Motoroller 60 150 21	
Stall torque	Cn0	Nm	3,2	
Peak torque	Cpk	Nm	10	
Rated torque	Cn	Nm	2,8	
Rated working speed	nM	rpm	800	
Rated voltage	Un	Vdc	60	
Maximum working speed @ 60Vdc	nmax	rpm	1200	
Rated output power	Pn	W	235	
Stall current	InO	Arms	7	
Peak current	lpk	Arms	23	
Rated current	In	Arms	5,2	
Torque constant	Kt	Nm/ Arms	0,53	
Voltage constant	Ke	Vrsm/ Krpm	31,8	
Phase/phase resistance @25°C	Rff	Ohm	0,5	
Phase/phase inductance	Lff	mH	1,8	
Electrical time constant	Te	ms	3,6	
Rotor inertia	Jm	Kg cm²	16,8	
Motor weight	m	Kg	5,3	
Axial shaft load @800 rpm	Fa	Ν	140	
Radial shaft load @800 rpm	Fr	N	600 (applied on the motor's centering)	

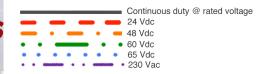


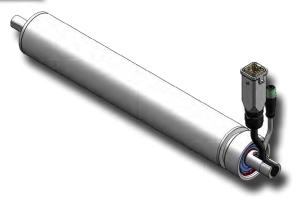
# **MOTOROLLER 60 POWER PACK DIMENSIONS**

### Motoroller 60 150 Ø 31,56° □ 24,2 10 Ø 14,2 89,7 Dett. A 1550 ± 50 **(** M8 20 Dimensions in mm M22 x 1.5 0,015 \_ 17 \_\_\_23 Ø 22 36 37 <sup>+0,3</sup> 38 +0,3 356,5 37,5 399 -0.5 474 <sup>+0,8</sup> <sub>-0,8</sub> 5W3 POWER cable Pre SIGNAL cable POWER CONNECTOR HAN Q/O-M-C 6p MS 1 = PHASE U 2 = PHASE V 3 = PHASE W 4 = . 5 = . 6 = PE SIGNAL CONNECTOR M12 5p MS 1 = HALL U 2 = HALL V 3 = HALL W 4 = 5/12 VDC 5 = GND

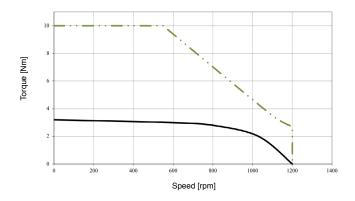


# MOTOROLLER 60 TORQUE /SPEED CHARTS





# **MOTOROLLER 60 150 21**



# **MOTOROLLER 76 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified

Continuous F Totally enclosed. Self-cooled NTC

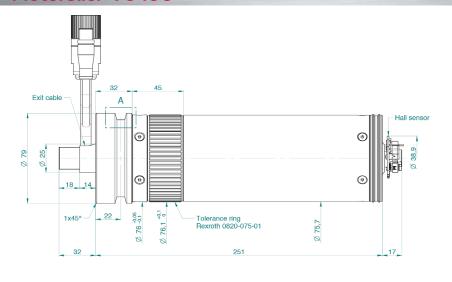
AMBIENT TEMPERATURE 0 to 40 °C
AMBIENT HUMIDITY 5 to 85% (non-condensing)
POLES 28 UL RECOGNIZED

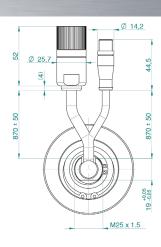
cURus E468964

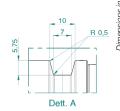
			Motoroller 76 100 14	
Stall torque	Cn0	Nm	3,6	
Peak torque	Cpk	Nm	22	
Rated torque	Cn	Nm	3,1	
Rated working speed	nM	rpm	800	
Rated voltage	Un	Vdc	60	
Maximum working speed @ 48Vdc	nmax	rpm	800	
Maximum working speed @ 65Vdc	nmax	rpm	1000	
Rated output power	Pn	W	260	
Stall current	InO	Arms	6,1	
Peak current	lpk	Arms	41	
Rated current	In	Arms	5,2	
Torque constant	Kt	Nm/ Arms	0,59	
Voltage constant	Ke	Vrsm/ Krpm	36	
Phase/phase resistance @25°C	Rff	Ohm	0,51	
Phase/phase inductance	Lff	mH	0,7	
Electrical time constant	Te	ms	1,37	
Rotor inertia	Jm	Kg cm²	23,2	
Motor weight	m	Kg	5,1	
Axial shaft load @800 rpm	Fa	Ν	220	
Radial shaft load @800 rpm	Fr	Ν	500 (applied on the rotor's centering)	

# **MOTOROLLER 76 FRAMELESS DIMENSIONS**

# Motoroller 76 100







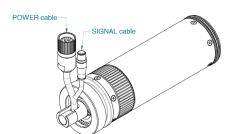


# POWER CONNECTOR Hypertac 6p MS

1 = -2 = PHASE U 3 = PHASE V 4 = PHASE W 5 = -6 = PE



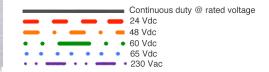
SIGNAL CONNECTOR M12 5p MS 1 = HALL U 2 = HALL V 3 = HALL W 4 = 5V 5 = GND





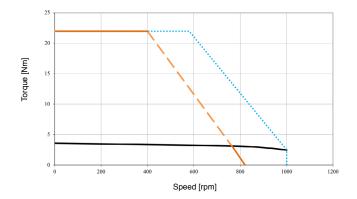


# **MOTOROLLER 76 TORQUE /SPEED CHARTS**





# **MOTOROLLER 76 100 14**



SEE IT BEFORE IT HAPPENS

# PALLET CONVEYOR MOTOROLLER 70 RATINGS AND SPECIFICATIONS

TIME RATING INSULATION CLASS ENCLOSURE

THERMAL PROTECTION

CE certified

S3 1'/2' (Ton = 1' / Toff = 2')

Totally enclosed. Self-cooled

PT1000

AMBIENT TEMPERATURE

0 to 40 °C

AMBIENT HUMIDITY 5 to 85% (non-condensing)

**POLES** 8

INSULATION SYSTEM UL /CSA cURus, DV155J File nr.:E216686

			Pallet Conveyor Motoroller 70 045 01	Pallet Conveyor Motoroller 70 045 04
Stall torque*	Cn0	Nm	25	25
Peak torque**	Cpk	Nm	40	40
Rated torque *	Cn	Nm	25	25
Rated working speed @ 24Vdc		m/s	0,26 (70 rpm)	0,12 (32,5 rpm)
Rated working speed @ 48Vdc		m/s	0,37 (101 rpm)	0,24 (65,7 rpm)
Rated output power @ 24Vdc	Pn	W	185	85
Rated output power @ 48Vdc	Pn	W	265	170
Rated voltage	Un		24-48 Vdc	24-48 Vdc
Stall current*	InO	Arms	9,5	4,8
Peak current	lpk	Arms	14,2	7,2
Rated current*	In	Arms	10,5	5,2
Torque constant	Kt	Nm/Arms	0,094	0,187
Voltage constant	Ke	Vrsm/Krpm	5,7	11,3
Phase/phase resistance @25°C	Rff	Ohm	0,16	0,67
Phase/phase inductance	Lff	mH	0,48	2,1
Electrical time constant	Te	ms	3,0	3,1
Rotor inertia	Jm	Kg cm²	0,300	0,300
Axial load @76 rpm	Fa	N	<b>350</b> (applied on the rotor's	<b>350</b> (applied on the rotor's
			middle)	middle)
Radial shaft load @76 rpm	Fr	N	1500 (distributed on the rotor)	1500 (distributed on the rotor)

<sup>\*</sup> Rating perfomances@ 20°C \*\* Peak torque max duration : 2s



# PALLET CONVEYOR MOTOROLLER 70 DIMENSIONS - type 01

# Pallet Conveyor Motoroller 70 045 power pack reference drawing 01

# 52 B B 26 24.6 M10 ₹ 20 M10 ₹ 20 Vista A

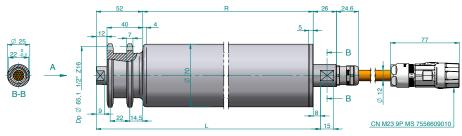
CONNECTIONS

POLE NR.	COLOR	FUNCTION
1	Brown/Green	+5V
2	White/Green	GND
2	Gray	Hall U
4	Pink	Hall W
5	Yellow	Hall V
Α	Blue	Phase U
В	Brown	Phase W
С	Black	Phase V
PE	Green/Yellow	Earth/PE

Dimensions in mm

(R) different length available on request

# Pallet Conveyor Motoroller 70 045 power pack reference drawing 02



Dimensions in mm

(R) different length available on request

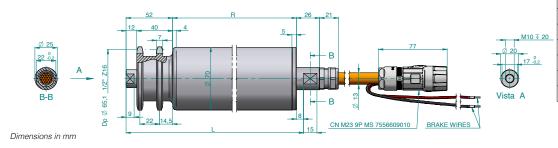
#### **CONNECTIONS**

M10 ∓ 20

Vista A

-	POLE NR.	COLOR	FUNCTION
	1	Brown/Green	+5V
	2	White/Green	GND
	2	Gray	Hall U
	4	Pink	Hall W
	5	Yellow	Hall V
	А	Blue	Phase U
	В	Brown	Phase W
	С	Black	Phase V
	PE	Green/Yellow	Earth/PE

# Pallet Conveyor Motoroller 70 045 power pack reference drawing 03



(R) different length available on request

#### **CONNECTIONS**

POLE NR.	COLOR	FUNCTION
1	Brown/Green	+5V
2	White/Green	GND
2	Gray	Hall U
4	Pink	Hall W
5	Yellow	Hall V
А	Blue	Phase U
В	Brown	Phase W
С	Black	Phase V
PE	Green/Yellow	Earth/PE

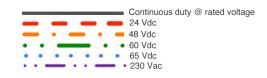
#### **BRAKE WIRES**

COLOR	FUNCTION
Red	Brake +
Black	Brake -



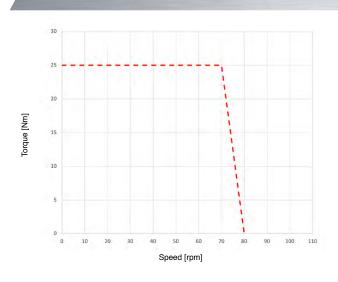


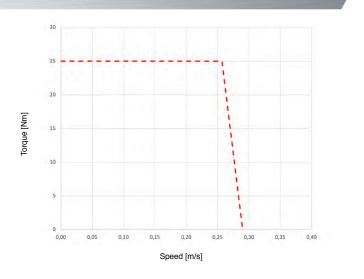
# **PALLET CONVEYOR 70 045 TORQUE/SPEED CHARTS**



# **MOTOROLLER 70 045 01**

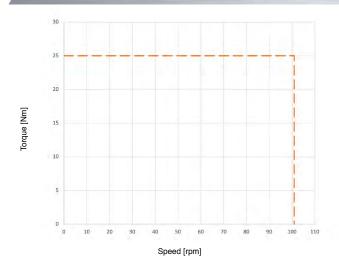
# 24Vdc

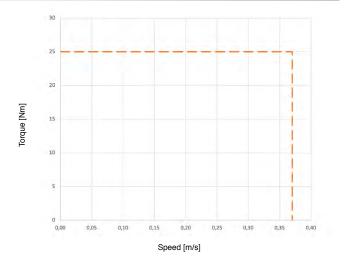




# **MOTOROLLER 70 045 01**

## 48Vdc

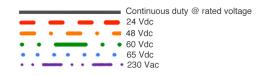






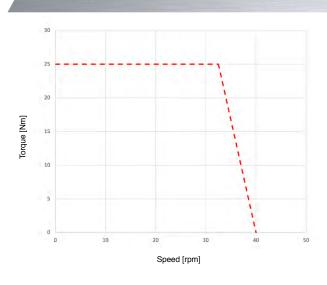


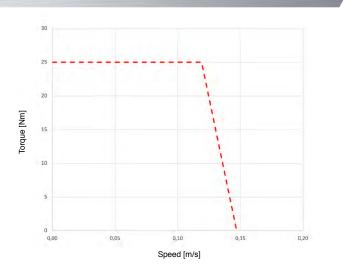
# PALLET CONVEYOR 70 045 TORQUE/SPEED CHARTS



# **MOTOROLLER 70 045 04**

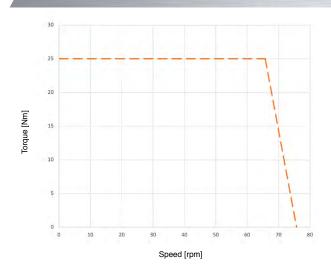
# 24Vdc

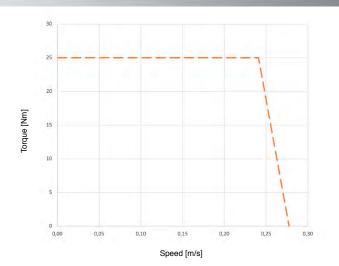




# **MOTOROLLER 70 045 04**

# 48Vdc









# PALLET CONVEYOR MOTOROLLER 89 RATINGS AND SPECIFICATIONS

POLES

TIME RATING INSULATION CLASS ENCLOSURE

CE certified

S3 1'/2' (Ton = 1' / Toff = 2') THERMAL PROTECTION

Totally enclosed. Self-cooled PT1000

AMBIENT TEMPERATURE AMBIENT HUMIDITY

0 to 40 °C

5 to 85% (non-condensing)

INSULATION SYSTEM UL /CSA cURus, DV155J File nr.:E216686CE

			B.II.4 O
			Pallet Conveyor Motoroller 89 045 04
Gear ratio			51:1
Stall torque*	Cn0	Nm	73
Peak torque**	Cpk	Nm	120
Rated torque *	Cn	Nm	62,5
Rated working speed		m/s	0,21 (44,4 rpm)
Rated output power	Pn	W	290
Rated voltage	Un		48 Vdc
Stall current*	InO	Arms	8,8
Peak current	lpk	Arms	15
Rated current*	In	Arms	8,4
Torque constant	Kt	Nm/Arms	0,187
Voltage constant	Ke	Vrsm/ Krpm	11,3
Phase/phase resistance @25°C	Rff	Ohm	0,64
Phase/phase inductance	Lff	mH	1,8
Electrical time constant	Te	ms	2,8
Rotor inertia	Jm	Kg cm²	0,526
Axial load @80 rpm	Fa	N	240 (applied on the rotor's middle)
Radial shaft load @80 rpm	Fr	Ν	3800 (applied on the rotor's middle)

<sup>\*</sup> Rating perfomances@ 20°C \*\* Peak torque max duration : 2s



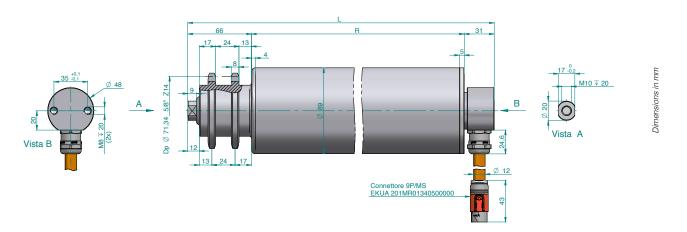
#### PALLET CONVEYOR MOTOROLLER 89 DIMENSIONS - type 01

#### MTR 89 045 - TYPE 01

 $\begin{array}{lll} \text{R} & & 922 \text{ mm} \\ \text{L}^* & & 1000 \text{ mm} \\ \text{Weight} & & 22,5 \text{ Kg} \end{array}$ 

(\*) different length available on request

#### Pallet Conveyor Motoroller 89 045 power pack reference drawing 01



(R) different length available on request

#### CONNECTIONS

N° PIN	WIRE COLOR	FUNCTION
1	Bn/Gn	+5V
2	Wh/Gn	GND
3	Gray	HALL U
4	Pink	HALL W
5	Yellow	HALL V
А	Blue	Phase U
В	Brown	Phase W
С	Bk	Phase V
PE	Gn/Ye	Earth/PE

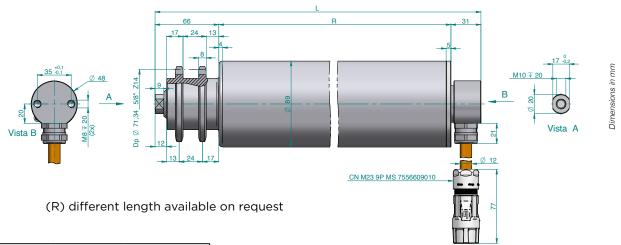


### PALLET CONVEYOR MOTOROLLER 89 DIMENSIONS - type 02

#### MTR 089 45 - TYPE 02

R 898 mm L\* 960 mm Weight 22,4 Kg \*different length available on request

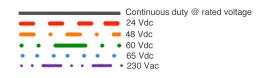
#### Pallet Conveyor Motoroller 89 045 power pack reference drawing 02



CONNECTIONS			
N° PIN	WIRE COLOR	FUNCTION	
E	Bn/Gn	+5V	
F	Wh/Gn	GND	
G	Gray	HALL U	
Н	Pink	HALL W	
L	Yellow	HALL V	
А	Blue	Phase U	
В	Brown	Phase W	
С	Bk	Phase V	
PE	Gn/Ye	Earth/PE	

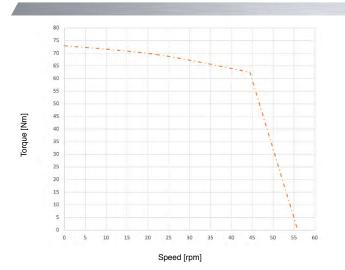


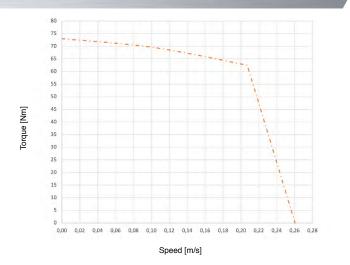
# PALLET CONVEYOR MOTOROLLER 89 TORQUE /SPEED CHARTS



#### **MOTOROLLER 89 045 04**

#### 48Vdc







#### **FEEDBACK FEATURES**

#### H1 HALL SENSOR

Motor size		Motoroller 46 -60- 76
Nominal Voltage	V	5-9 ±5%
Nominal current	mA	100
Electronic type	_	OPEN COLLECTOR
N° of pulses revolution	ppr	84

#### E1 INCREMENTAL ENCODER

Motor size		Motoroller 46 -60- 76
Nominal Voltage	Vdc	5-9 ±5%
Nominal current	mA	100
Electronic type		OPEN COLLECTOR
Zero impulse		ONE AT A LAP
N° of pulses revolution	ppr	896
Resolution	cpr	3584

#### **E2 INCREMENTAL ENCODER**

Motor size		Motoroller 46 AD	
Nominal Voltage	Vdc	5-9 ±5%	
N° of pulses revolution	ppr	7168	



# >>> PERFECTLY MATCHED DRIVES:

MAXIMIZING PERFORMANCE AND EFFICIENCY

# DMR SERVO DRIVES

The DMR series is a series of customized drives dedicated to logistic automation market.

The series features two models: DMR 50-5/50, DMR76-10/65 and DMR PC 6/50, designed and manufactured for driving gearless motorollers, exploiting its technological advantages based on direct drive without any gear for motion transmission.

#### DMR 50-5/50 FEATURES

- DUAL AXES OPERATION CAPABILITY
- > PERFECT MATCH WITH GEARLESS MOTOROLLER

#### MTR46

- > I/O PROGRAMMABILITY
- > FUSE PROTECTION
- > CROSSBELT FUNCTIONALITY
- > CONVEYOR FUNCTIONALITY
- > SPEED AND ACCELERATION PROGRAMMABILITY
  - CE

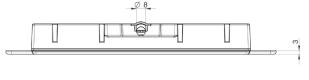
- > HALL SENSOR AND ENCODER FEEDBACK
- > DMR BROWSER SOFTWARE INTERFACE
- > RS 485 PROGRAMMING INTERFACE
- > CAN OPEN FIELDBUS
- > PHOTO EYE SUPPORT
- > 2 INPUT, 2 OUTPUT RELAY EACH AXIS

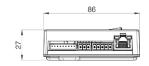


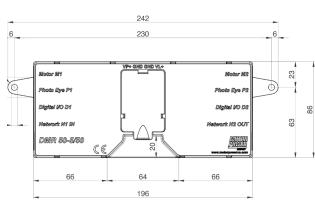
### DMR 50-5/50 PRODUCT DATA

FEATURE	UNITS	DMR 50-5/50
Rated output power	W	180 each axis
Efficiency at rated power	%	>95
Operating supply voltage	Vdc	12-60
Typical supply voltage	Vdc	48
Maximum operating voltage	Vdc	80
Auxiliary supply voltage		24 V (8-30)
Rated output current	Arms	5
Peak output current	Arms	15
Peak time	S	3
PWM switching frequency	kHz	16 kHz
Maximum outputfrequency	Hz	<600
Commutation		Sinusoidal and space vector
Dimensions	WxDxH mm	196x70x27
Working temperature	°C	-20 ÷ +55
Storage temperature	°C	-40 ÷ +75
Humidity	%	85% not consdensing
Altitude without derating	m	1000
IP protection	IP	20

# DMR 50-5/50 PRODUCT DIMENSIONS









Dimensions in mm

### DMR 50-5/50 PRODUCT DATA

MOTOR CONNECTION		
PIN	NAME	
1	Phase U	
2	Phase V	
3	Phase W	
4	Thermal sensor	
5	Power supply 5V	
6	ov	
7	Hall U/Inc A	
8	Hall V/Inc B	
9	Hall W/Inc Z	

PHOTO EYE INPUT	
PIN	NAME
1	24V
2	GND
3	Photo eye input

POWER CONNECTION		
PIN	NAME	
1	24V logic	
2	0 V	
3	48 V power	

I/O DEFINITION			
PIN	DIRECTION	FUNCTION	
1	Input	Enable	
2	Input	Dir	
3	Input	Analogf Input	
4	Output	Fault	
5	Output	Configurable	

# **DMR SERVO DRIVES**

DMR 76-10/65 HP is a digital drive for motorollers in cross belt applications. Main features of this drive are current digital control achieved with the technique of vector space and updated with a 10 kHz frequency. Speed digital loop with proportional-integral compensator updated with 10 kHz frequency. Position digital loop with proportional compensator and handling of dead zone updated with 10 kHz frequency. Digital Profibus interface for connecting to supervisor PLC. Motor feedback interface via Hall sensors.

#### DMR 76-10/65 FEATURES

- > THE PERFECT MATCHED DRIVE FOR GEARLESS
- **MOTOROLLER MTR 76**
- > USB PROGRAMMING INTERFACE
- > PROFIBUS FIELBUS DP V1
- > I/O PROGRAMMABILITY
- > I/O PROXY DUAL LOOP
- ( (

- > DMR BROWSER SOFTWARE INTERFACE
- > FUSE PROTECTION
- > CROSSBELT FUNCTIONALITY
- > SPEED AND ACCELERATION PROGRAMMABILITY
- > HALL SENSOR AND ENDECODER FEEDBACK
- > 2 INPUT, 2 OUTPUT RELAY



### DMR 76-10/65 PRODUCT DATA

FEATURE	UNITS	DMR 76-10/65
Rated output power	W	650
Efficiency at rated power	%	>95
Operating supply voltage	Vdc	24-80
Typical supply voltage	Vdc	48-65
Maximum operating voltage	Vdc	85
Auxiliary supply voltage		-
Rated output current	Arms	10
Peak output current	Arms	50
Peak time	S	0,75 on 20s
PWM switching frequency	kHz	16 kHz
Maximum outputfrequency	Hz	<600
Commutation		Sinusoidal and space vector
Dimensions	WxDxH mm	250x150x45
Working temperature	°C	-20 ÷ +55
Storage temperature	°C	-40 ÷ +75
Humidity	%	85% not consdensing
Altitude without derating	m	1000
IP protection	IP	54 on drive front 40 on the whole drive



# DMR 76-10/65

#### DMR 76-10/65 PRODUCT DATA

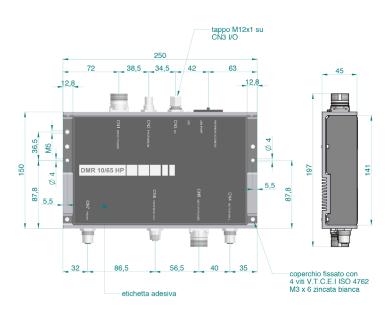
#### HARDWARE AND FIRMWARE CHARACTERISTICS

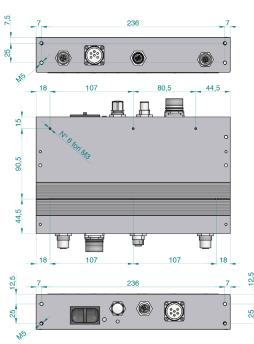
- > ONE ELECTRONIC BOARD FOR CONTROL LOGIC AND POWER
- > ONE SUPPLY FOR ELECTRONIC CONTROL AND MOTOR OUTPUT STAGE
- > PROFIBUS SLAVE COMMAND INTERFACE WITH DIP SWITCH NODE ADDRESS SELECTION
- > USB DEVICE INTERFACE FOR CONFIGURATION AND MAINTENANCE
- > CONTROL THROUGH SINUSOISAL ALGORITHM AND HALL SENSOR FEEDBACK
- > GENERIC I/O PROGRAMMABILITY
- > I/O PROXI PROGRAMMABILITY

#### INTERFACE

> THIS DRIVE IS EQUIPPED WITH SOFTWARE USER INTERFACE "DMR BROWSER" FOR OPERATING, MONITORING AND SUPERVISION OF THE APPLICATION. REFER TO THE APPROPRIATE MANUAL FOR INSTALLATION INSTRUCTIONS AND USE.

#### **PRODUCT DIMENSIONS**







# DMR 76-10/65

### CONNECTION

DRIVE POWER	
PIN	NAME
1	V+
2	-
3	-
4	-
5	V-
6	-

PROFIBUS IN		
PIN	NAME	
1	-	
2	DATA-/A-LINE	
3	-	
4	-	
5	DATA+/B-LINE	

PROFIBUS OUT		
PIN	NAME	
1	V+	
2	DATA-/A-LINE	
3	$V_{REF}$	
4	DATA+/B-LINE	
5	-	

DIGITAL I/O	
PIN	NAME
1	OUT1 COM
2	INRET 123
3	+24V <sub>DC</sub>
4	OUT1 NC
5	IN1
6	IN2
7	IN3
8	GND (+24 V <sub>DC</sub> )

# CONNECTION

MOTOR OUTP	UT
PIN	NAME
1	-
2	U
3	V
4	W
5	-
6	PE

FEEDBACK	
PIN	NAME
1	U/A
2	V/B
3	W/Z
4	5V <sub>DC</sub>
5	GND

PROXY DUAL LOOP		
PIN	NAME	
1	+24V <sub>DC</sub> PROXY	
2	INRET 123 PROXY	
3	GND (+24V <sub>DC</sub> )	
4	OUT2 NO	
5	OUT2 NO	
6	IN7 PROXY	
7	+24 V <sub>DC</sub>	
8	OUT2 COM	





# SERVO DRIVE

The LITE PRO series is represented by the extremely compact 4-quadrants drives perfect matched to control motoroller 60. This series features as standard CanOpen interface and a complete programmable version with integral Motion Process Unit, that allows stand alone and network architecture operation.

#### **FEATURES**

- > STANDARD FEEDBACK TTL ENCODER
- AND HALL SENSOR
- > DIGITAL I/O: UP TO 8 DIGITAL

**INPUTS AND 1 OR 2 DIGITAL OUTPUTS** 

**CUSTOMIZIBLE WITH SEVERAL BUILT-IN** 

**FUNCTIONS** 

- > CONTROL: STANDARD PI CONTROL LOOP
- > SERVO MODES: TORQUE, VELOCITY AND

**POSITION WITH S-CURVE PROFILE** 

- > INTERNAL SCRIPT
- > EXTREME COMPACT DESIGN
- > USB PROGRAMMING KEY

#### INTERFACE

- > ANALOG VELOCITY AND TORQUE COMMAND ± 10V
- > CANopen







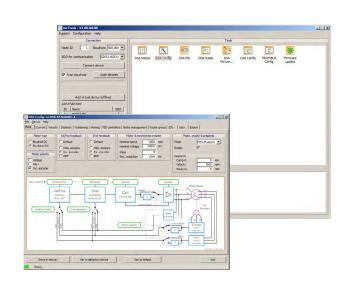
# COMPACT AND PROFITABLE

### **PRODUCT DATA**

FEATURE	UNITS	LPRO E40
Input voltage	VDC	48
Efficiency at rated power	%	>95
Auxiliary supply voltage	VDC	9 30
Continuous current	Arms	8
Peak current	Arms	24
Ambient operating temperature	°C	0 to + 40°
Maximum humidity	%	5÷85% not condensing
Mounting method		Wall mounting DIN Rail
Dimensions	LxWxH mm	110x22,5x77
Weight	gr	110
Digital IN		4
Digital OUT		1

### LITE PRO USER INTERFACE

- > EASY AND INTUITIVE PC SOFTWARE ALLOWS A FAST PARAMETERIZATION OF THE LITE PRO
- > SIMPLE SCOPE
- > SCRIPT EDITING





# DMR SERVO DRIVES

Introducing our DMR PC-6/50 Dual Axis Drives - the ideal solution for bundling with Pallet Conveyor Motorollers 70 and 89. This drive is engineered to ensure optimal performance, reliability, and precise control and accuracy in handling large, heavy items, including pallets. Typically used at the end of the line in material handling applications, this drive feature easy and intuitive commissioning for advanced motion control of two motorollers.

#### DMR PC-6/50 FEATURES

- > DUAL AXES OPERATION CAPABILITY
- > PERFECT MATCH WITH PALLET CONVEYOR 70 AND

#### 89

- > I/O PROGRAMMABILITY
- > SPEED AND ACCELERATION PROGRAMMABILITY
- > HALL SENSOR FEEDBACK



- > DMR BROWSER SOFTWARE INTERFACE
- > PROFINET I/O, ETHERNET IP, (for each axes)

#### **ETHERCA**1

- > 3 PHOTO EYE SUPPORT FOR EACH AXIS
- > 2 INPUT, 2 OUTPUT
- > 10V ANALOG INPUT





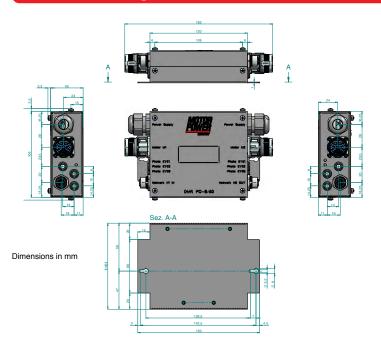


#### DMR PC 6/50 PRODUCT DATA

FEATURE	UNITS	DMR PC 6/50
Rated output power	W	350 each axis
Efficiency at rated power	%	>95
Operating supply voltage	Vdc	12-60
Typical supply voltage	Vdc	48
Maximum operating voltage	Vdc	80
Auxiliary supply voltage		24 V (8-30)
Rated output current	Arms	6
Peak output current	Arms	20
Peak time	S	3
PWM switching frequency	kHz	16 kHz
Maximum outputfrequency	Hz	<600
Commutation		Sinusoidal and space vector
Dimensions	WxDxH mm	182 x 105 x 45
Working temperature	°C	-20 ÷ +55
Storage temperature	°C	-40 ÷ +75
Humidity	%	85% not consdensing
Altitude without derating	m	1000
IP protection	IP	20



## DMR PC-6/50 PRODUCT DIMENSIONS





### DMR PC-6/50 PRODUCT DATA

MOTOR CONNECTION			
PIN	FUNCTION	DESCRIPTION	
1	Feedback Power Supply	5Vdc	
2	Gnd	0 Vdc	
3	Hu	Hall Sensor u	
4	Hv	Hall Sensor v	
5	Hw	Hall Sensor w	
Α	Mu	Motor Phase	
В	Mv	Motor Phase	
С	Mw	Motor Phase	
FE	Functional earth	Functional earth	

POWER SUPPLY			
PIN	FUNCTION	DESCRIPTION	
1	VP+	Power Supply 48Vdc	
2	GND	0 Vdc	
4	VL+	Logic Supply 24Vdc	

PHOTO EY	E PG AND INTERNA	AL CONNECTOR	
PIN	FUNCTION	DESCRIPTION	
1	Power Supply	24 V power supply	
2	Photo Eye Input 1	Input Signal	
3	Gnd	0 Vdc	
4	Power Supply	24 V power supply	
5	Photo Eye Input 2	Input Signal	
6	Gnd	0 Vdc	
7	Power Supply	24 V power supply	
8	Photo Eye Input 3	Input Signal	
9	Gnd	0 Vdc	



NOIE			



NOTE			



**MOTORS** 

**MOTION CONTROL** 

**MECHATRONICS** 



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