

# VIIR - GEARLESS MOTOROLLER

INNOVATION IN INTRALOGISTIC SMART SOLUTION





# MTR - GEARLESS MOTOROLLER

# INTRODUCING THE FUTURE IN SORTING AND MATERIAL HANDLING TECHNOLOGY

Motor Power Company www.motorpowerco.com info@motorpowerco.it

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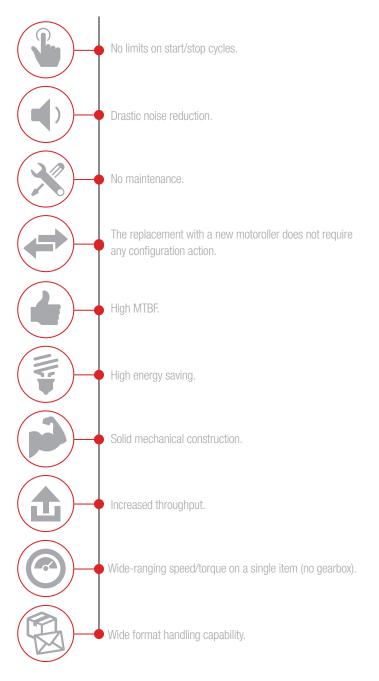


otor Power Company keeps developing new concepts in sorting and material handling. Our goal is sharing with the market our domain expertise in intralogistics; innovative solutions through our gearless and geared technology products. We propose motion control bundles composed by gearless motorollers and smart drives. All our solutions are in-house developed and are particularly oriented for control, movement, storage and protection of materials and products throughout manufacturing, sorting, warehousing, distribution, consumption and disposal. Motor Power Company specialises in the design, development and manufacturing of high performance industrial motion solutions. We have acquired consolidated expertise and technical know-how from 30 years experience with all kinds of applications and through our continuous commitment to research and development. This allows us to partner leading international companies in the supply of products and solutions for automation and motion control.

## Gearless motorollers and drives.

## Increased efficiency and limitless performances

Motor Power Company introduces these perfect matched bundles costituted by gearless motorollers and smart drives. Everything has been conceived as a specific product for conveyor, crossbelt or any roller transfer systems. Two versions are proposed; *frameless cartridges* without tube, to be inserted into the roller to be moved, and *power pack* version, a ready to use motoroller embedded in its own tube. The technology on which the motor is based comes from the direct drive torque motors. Consequently, the motion is transmitted directly from the motoroller to the load, without any gears.





Motoroller without gears ensures:

- > High MTBF, as the motoroller needs less components than the standard kinematic chain
- > System efficiency increase due to the absence of gears inside the motoroller
- > Accuracy, due to the feedback reliability
- > High dynamic thanks to the direct drive technology
- > Easy replacement, with the autotuning system of DMR Drives, the substitution with a new motoroller does not require any configuration action
- > Easy commissioning, due to a unique part number, there are no different gearbox ratios to handle according to different speed needs.
- > Wide speed availability, one motoller for all speed range





## The gearless motoroller series at a glance

# Gearless motoroller 46 - cartridge version 800rpm@24-48 Vdc

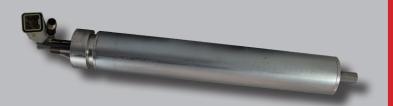


Frameless gearless cartridge motoroller for general conveyor applications. Suitable for 50mm roller tube integration, roller tube range available on request

### Features

- » Two models
- » Rated power 50 Watt and 115 Watt
- » Rated torque 0,6 Nm and 1,35 Nm
- » Hall sensors and encoder feeback for higher precision
- » Cartridge diameter 46 mm suitable for all 50 mm diameter tube
- » 24 and 48Vdc power supply
- » Full speed control
- » Wide roller customization

# Gearless power pack motoroller 60 800rpm@60 Vdc



Tube equipped gearless motoroller for cross belt driving and controlling.

### Features

- » Ready to use motoroller 60mm diameter
- » Rated power 235 Watt
- » Rated torque 2,8 Nm
- » 60Vdc power supply
- » Full speed control

Gearless motoroller 76
Cartridge version
800rpm@48-65 Vdc

Gearless cartridge motoroller for cross belt driving and controlling.
Suitable for 80mm roller tube integration, roller tube range available on request

### **Features**

- » Rated power 260 Watt
- » Rated torque 3,1 Nm
- » Encoder feeback for higher precision
- » Cartridge diameter 76 mm suitable for alla 80 mm diameter tube
- » 48 and 65 Vdc for power supply
- » Full speed control
- » Wide roller customization

MOTOD



## The drive series at a glance



### **Features**

- » Dual axes operation
- » 24 and 48 Vdc operating supply voltage
- » Encoder and Hall Sensor feeback
- » CanOpen Fieldbus
- » RS485 programming interface
- » I/O programmability for speed, start and stop control



### Lite Pro drive

Lite Pro drive is ideal for controlling motoroller 60

### **Features**

- »24 and 48 Vdc operating supply voltage
- » Encoder and Hall Sensor feeback
- » CanOpen Fieldbus
- » I/O programmability for speed, start and stop control



### Features

- » 24 and 65 Vdc operating supply voltage
- » Encoder and Hall Sensor feeback
- » Profibus Fieldbus
- » I/O programmability for speed, start and stop control
- » I/O proxy dual loop

SEE II BEFURE II HAPPENS



## **PALLET CONVEYOR MOTOROLLER**

Pallet Conveyor allows efficient transport, accumulation, lifting and sorting of heavy loads as an alternative to forklifts handling.

In warehouse automation operations a pallet conveyor is generally utilized to move loads of several hundreds kilograms while ensuring continuous feed of work and cutting edge efficiency.

The high-performance synchronous brushless servomotor, coupled with planetary gearbox, ensures performance with loads up to 1500 kg per zone.



- > ROBUST MECHANICAL DESIGN
- > HIGH DYNAMICS
- > EASY CONVEYOR DESIGN
- > THE REPLACEMENT WITH A NEW MOTOROLLER DOES NOT REQUIRE ANY CONFIGURATION ACTION
- > HIGH MTBF
- > HIGH ENERGY SAVING



## Pallet conveyor MOTOROLLER



### **Features**

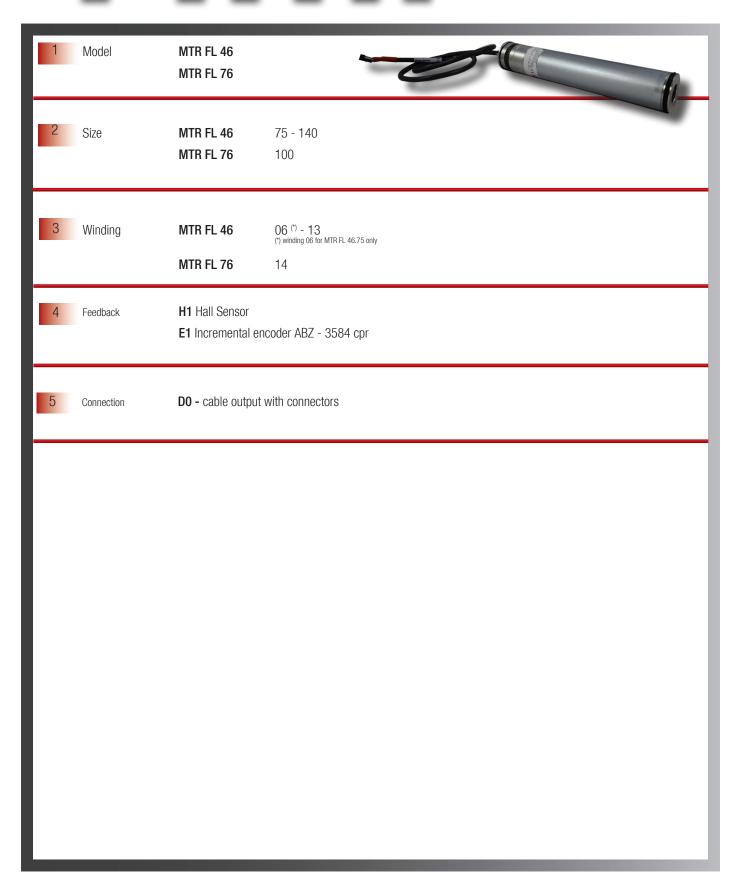
- » Reaty to use pallet conveyor motoroller
- » Rated power 400 Watt
- » Planetary gear box ratio 1:45
- » Tube diameter 89mm
- » Conveyor velocity 22,4 m/min (0,37 m/sec)
- » Load up to 1500 Kg
- » Supply voltage available: 48 Vdc, 230 Vac, 400 Vac



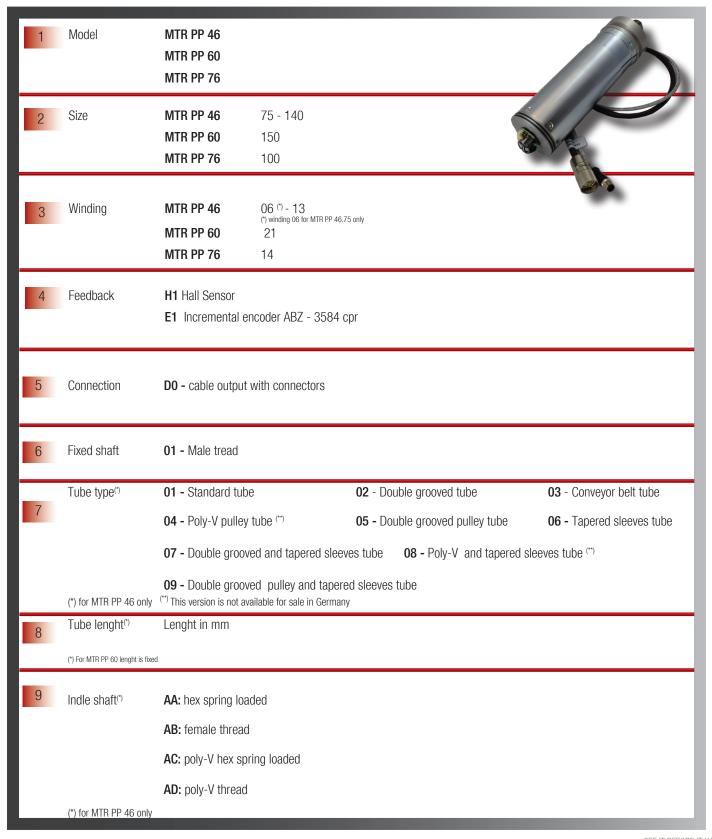










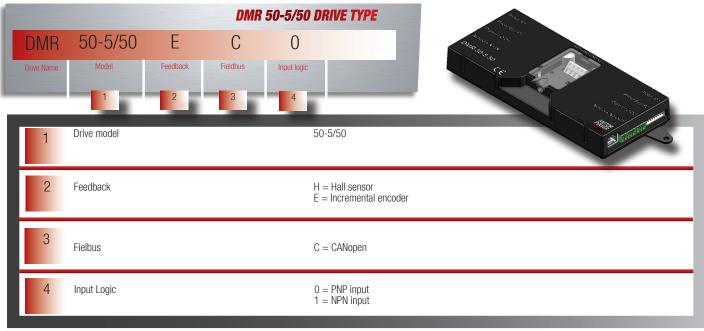


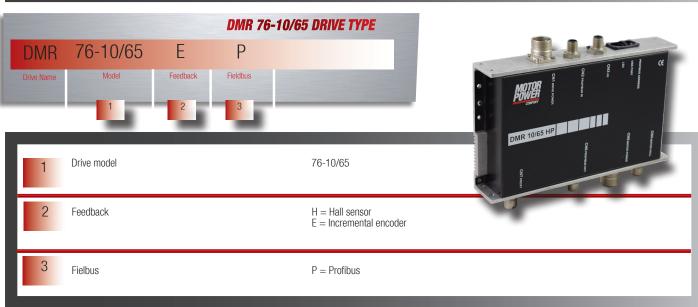


### PALLET CONVEYOR MOTOROLLER Power Pack MTR PP 89 045 04 H1 D0 01 01 800 AA XXX Winding Feedback Connection Fixed shaft Tube Indle shaft Tube type lenght 8 9

1	Model	MTR PP 89
2	Size	MTR PP 89 045
3	Winding	MTR PP 89 04 - 15
4	Feedback	H1 Hall Sensor
5	Connection	D0 - cable output with connectors
6	Fixed shaft	01 - Male tread
7	Tube type	01 - Standard tube
8	Tube lenght	Lenght in mm
9	Indle shaft	AA: hex spring loaded AB: female thread











1	Feedback	E = Hall sensor and encoder
2	Model (output current) Arms	40 = 8/24
3	Fielbus	C = CANopen

## **MOTOROLLER 46 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified Continuous F

Totally enclosed. Self-cooled NTC

AMBIENT TEMPERATURE AMBIENT HUMIDITY POLES

INSULATION SYSTEM UL /CSA

0 to 40 °C

5 to 85% (non-condensing)

28

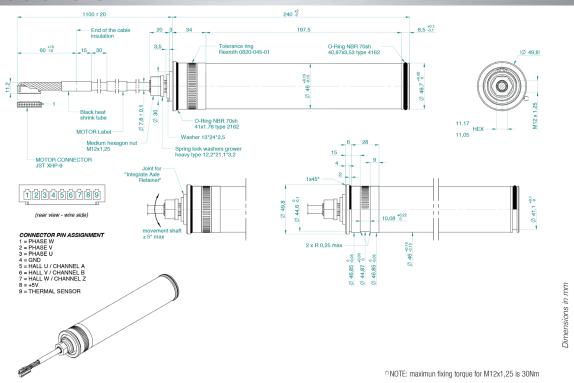
cURus, DV155J File nr.:E216686

			Motoroller 46 75 06	Motoroller 46 75 13	Motoroller 46 140 13
Stall torque	Cn0	Nm	0,74	0,74	1,5
Peak torque	Cpk	Nm	2,2	2,2	4,5
Rated torque	Cn	Nm	0,6	0,6	1,35
Rated working speed	nM	rpm	800	800	800
Rated voltage	Un	Vdc	24	48	48
Maximum working speed @ 24Vdc	nmax	rpm	1000	500	500
Maximum working speed @ 48Vdc	nmax	rpm	1150	1150	1000
Rated output power	Pn	W	50	50	115
Stall current	In0	Arms	3,3	1,63	3,3
Peak current	lpk	Arms	11	5,71	10,61
Rated current	In	Arms	2,7	1,33	3
Torque constant ±10%	Kt	Nm/Arms	0,22	0,45	0,45
Voltage constant ±10%	Ke	Vrsm/Krpm	13,6	27,6	27,6
Phase/phase resistance ±10% @25°C	Rff	Ohm	0,77	2,64	1,23
Phase/phase resistance ±10% @25°C	Lff	mH	1,35	5,4	2,81
Electrical time constant	Te	ms	1,75	2	2,3
Rotor inertia	Jm	Kg cm <sup>2</sup>	5	5	6,1
Motor weight	m	Kg	1,96	1,96	2,73
Axial shaft load @800 rpm	Fa	N		1	10
Radial shaft load @800 rpm	Fr	N		220 (applied on t	he rotor's centering)

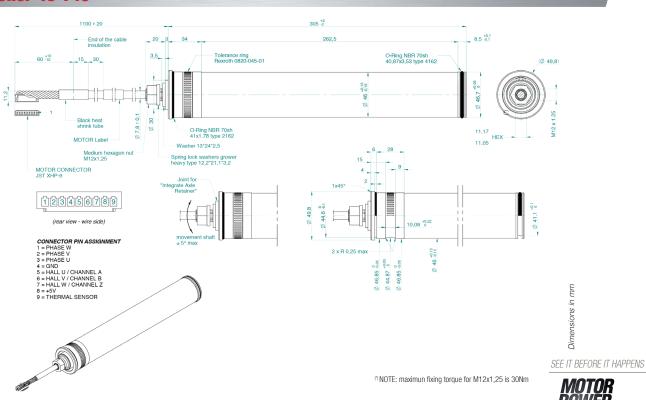


## **MOTOROLLER 46 FRAMELESS DIMENSIONS**

### **Motoroller 46 75**



### **Motoroller 46 140**

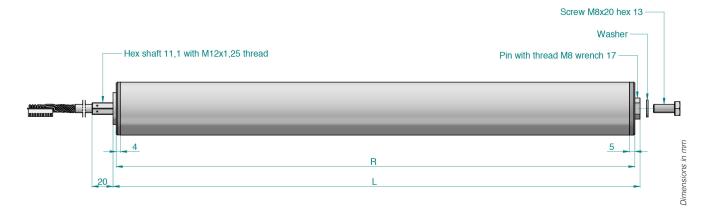


### SEE IT BEFORE IT HAPPENS

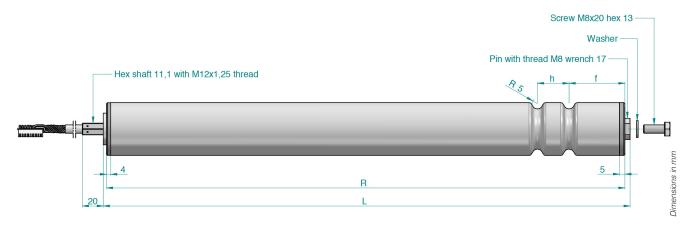
## **MOTOROLLER 46 POWER PACK TUBE TYPE**



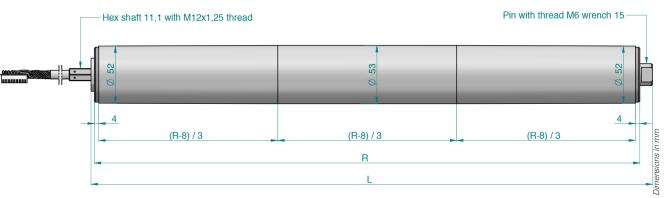
## **Motoroller 46 standard tube 01**



## Motoroller 46 double grooved tube 02



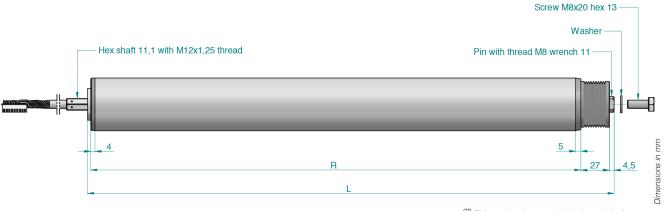
## Motoroller 46 conveyor belt tube 03



## **MOTOROLLER 46 POWER PACK TUBE TYPE**

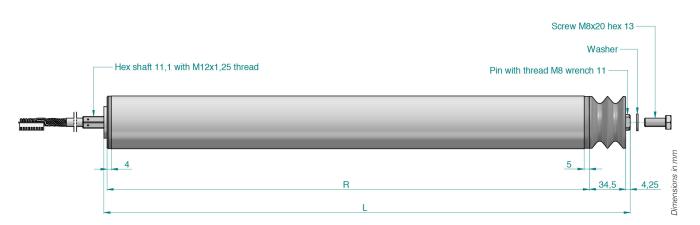


## Motoroller 46 poly-V pulley tube 04 "

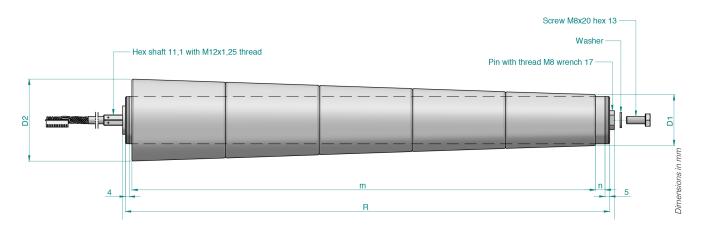


(\*\*) This version is not available for sale in Germany

## Motoroller 46 double grooved pulley tube 05



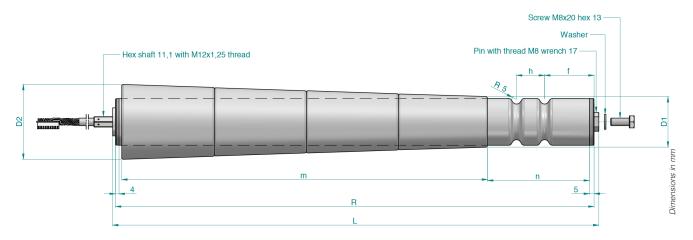
## Motoroller 46 tapered sleeves tube 06



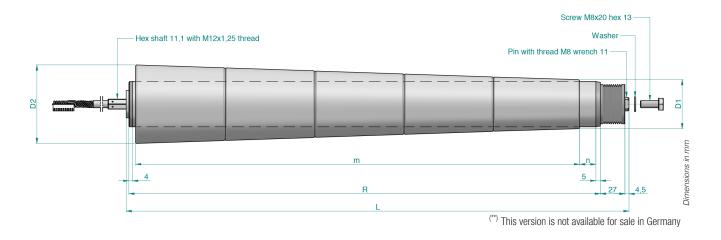
## **MOTOROLLER 46 POWER PACK TUBE VERSIONS**



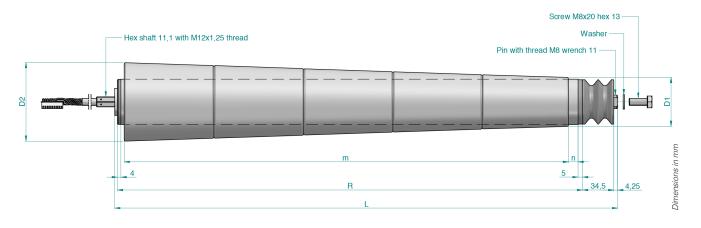
### Motoroller 46 double grooved and tapered sleeves tube 07



## Motoroller 46 poly-V pulley and tapered sleeves tube 08 "



## Motoroller 46 double grooved pulley and tapered sleeves tube 09

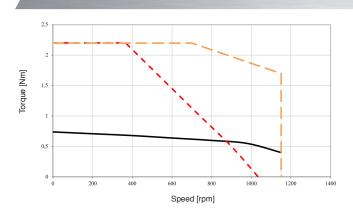


## **MOTOROLLER 46 TORQUE /SPEED CHARTS**

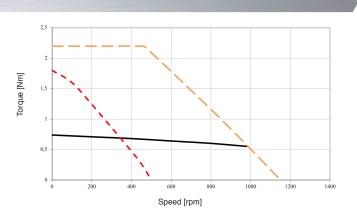




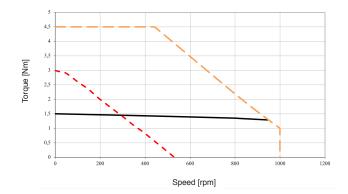
### **MOTOROLLER 46 75 06**



### **MOTOROLLER 46 75 13**



### **MOTOROLLER 46 140 13**



## **MOTOROLLER 60 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified Continuous F

Totally enclosed. Self-cooled NTC

AMBIENT TEMPERATURE AMBIENT HUMIDITY POLES INSULATION SYSTEM UL /CSA

5 to 85% (non-condensing) 28 cURus , DV155J File nr.:E216686

0 to 40 °C

### **Motoroller 60 150 21**

Stall torque	Cn0	Nm	3,2
Peak torque	Cpk	Nm	10
Rated torque	Cn	Nm	2,8
Rated working speed	nM	rpm	800
Rated voltage	Un	Vdc	60
Maximum working speed @ 60Vdc	nmax	rpm	1200
Rated output power	Pn	W	235
Stall current	In0	Arms	6,1
Peak current	lpk	Arms	23
Rated current	In	Arms	5,2
Torque constant ±10%	Kt	Nm/Arms	0,53
Voltage constant ±10%	Ke	Vrsm/Krpm	31,8
Phase/phase resistance ±10% @25°C	Rff	Ohm	0,5
Phase/phase resistance ±10% @25°C	Lff	mH	1,8
Electrical time constant	Te	ms	3,6
Rotor inertia	Jm	Kg cm <sup>2</sup>	16,8
Motor weight	m	Kg	5,3
Axial shaft load @800 rpm	Fa	N	140
Radial shaft load @800 rpm	Fr	N	600 (applied on the rotor's centering)



SEE IT BEFORE IT HAPPENS

## **MOTOROLLER 60 POWER PACK DIMENSIONS**

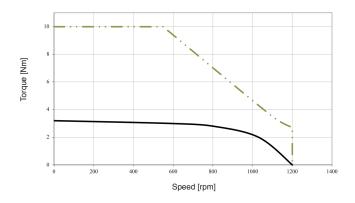
### **Motoroller 60 150** Ø 31,56° □ 24,2 10 Ø 14,2 89,7 Dett. A Α 1550 ± 50 M8 20 Ø 22 -0,025 M22 x 1.5 \_ 17 \_\_\_ 23 \_\_\_ 36 37 <sup>+0,3</sup> 356,5 37,5 399 -0.5 5W3 POWER cable SIGNAL cable Pre POWER CONNECTOR HAN Q/O-M-C 6p MS 1 = PHASE U 2 = PHASE V 3 = PHASE W 4 = . 5 = . 6 = PE SIGNAL CONNECTOR M12 5p MS 1 = HALL U 2 = HALL V 3 = HALL W 4 = 5/12 VDC 5 = GND

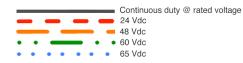


## **MOTOROLLER 60 TORQUE /SPEED CHARTS**



## **MOTOROLLER 60 150 21**







## **MOTOROLLER 76 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified

Radial shaft load @800 rpm

Continuous F

Totally enclosed. Self-cooled NTC

AMBIENT TEMPERATURE AMBIENT HUMIDITY POLES INSULATION SYSTEM UL/CSA

**Motoroller 76 100 14** 

500 (applied on the rotor's centering)

0 to 40 °C 5 to 85% (non-condensing) 28 cURus , DV155J File nr.:E216686

Stall torque	Cn0	Nm	3,6
Peak torque	Cpk	Nm	22
Rated torque	Cn	Nm	3,1
Rated working speed	nM	rpm	800
Rated voltage	Un	Vdc	60
Maximum working speed @ 48Vdc	nmax	rpm	800
Maximum working speed @ 65Vdc	nmax	rpm	1000
Rated output power	Pn	W	260
Stall current	ln∩	Arme	6.1

Ma Ma Ra Stall current In0 Arms 6,1 Peak current lpk Arms 41 Rated current In Arms 5,2 Torque constant ±10% Nm/Arms 0,59 Kt Voltage constant ±10% Ke Vrsm/Krpm 36 Phase/phase resistance ±10% @25°C Rff Ohm 0,51 Phase/phase resistance ±10% @25°C Lff mΗ 0,7 Electrical time constant Те 1,37 ms Rotor inertia Kg cm<sup>2</sup> 23,2 Jm Motor weight Kg 5,1 m Axial shaft load @800 rpm Ν Fa 220

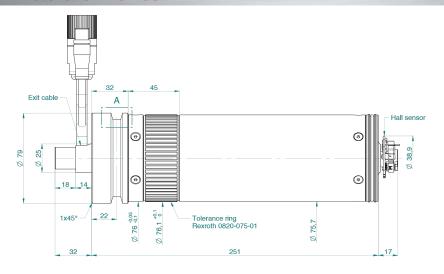
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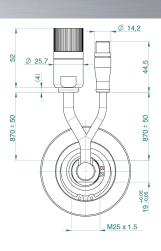
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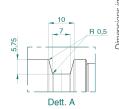
MOTOR POWER COMPANY

## **MOTOROLLER 76 FRAMELESS DIMENSIONS**

## **Motoroller 76 100**







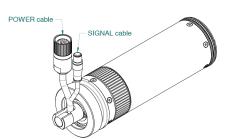


## POWER CONNECTOR Hypertac 6p MS

1 = -2 = PHASE U 3 = PHASE V 4 = PHASE W 5 = -6 = PE



SIGNAL CONNECTOR M12 5p MS 1 = HALL U 2 = HALL V 3 = HALL W 4 = 5V 5 = GND

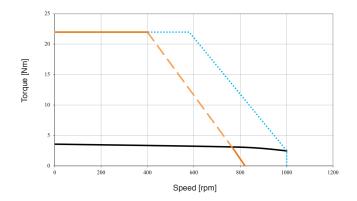




## **MOTOROLLER 76 TORQUE /SPEED CHARTS**



## **MOTOROLLER 76 100 14**



## **MOTOROLLER 89 RATINGS AND SPECIFICATIONS**

TIME RATING INSULATION CLASS ENCLOSURE THERMAL PROTECTION CE certified S3 1'/2' (Ton = 1' / Toff = 2') F

Totally enclosed. Self-cooled PT1000

AMBIENT TEMPERATURE AMBIENT HUMIDITY POLES

INSULATION SYSTEM UL/CSA

0 to 40 °C

5 to 85% (non-condensing)

8

cURus, DV155J File nr.:E216686

			Motoroller 89 045 04	Motoroller 89 045 15
Stall torque*	Cn0	Nm	73	73
Peak torque**	Cpk	Nm	120	120
Rated torque *	Cn	Nm	43	43
Rated working speed		m/s	0,27	0,31
Rated output power	Pn	W	335	355
Rated voltage	Un		48 Vdc	230 Vac
Stall current*	In0	Arms	9,8	2
Peak current	lpk	Arms	16,9	3,5
Rated current*	In	Arms	6,4	1,32
Torque constant ±10%	Kt	Nm/Arms	0,187	0,91
Voltage constant ±10%	Ke	Vrsm/Krpm	11,3	55
Phase/phase resistance ±10% @25°C	Rff	Ohm	0,67	13,3
Phase/phase resistance ±10% @25°C	Lff	mH	2,1	38,5
Electrical time constant	Te	ms	3,1	2,9
Rotor inertia	Jm	Kg cm <sup>2</sup>	0,526	0,526
Axial load @80 rpm	Fa	N	240 (applied on the rotor's middle)	240 (applied on the rotor's middle)
Radial shaft load @80 rpm	Fr	N	3800 (applied on the rotor's middle)	3800 (applied on the rotor's middle)
* Dating parfamanage 2000 ** Dook targue may a	luration . Oa			

<sup>\*</sup> Rating perfomances@ 20°C \*\* Peak torque max duration : 2s

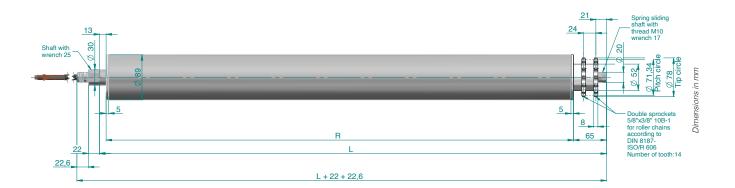


## **MOTOROLLER 89 DIMENSIONS - type 01**



R 922 mm L\* 1000 mm Weight 22,5 Kg

## Motoroller 89 045 power back reference drawing 01



SIGNAL CABLE			
WIRE COLOR	FUNCTION		
Green	Hall U		
Yellow	Hall U/		
Gray	Hall V		
Pink	Hall V/		
White	Hall W		
Brown	Hall W/		
Red	+5VCC		
Blue	GND		
Drain Wire	shield		

POWER CABLE				
WIRE COLOR	FUNCTION			
White	Phase U			
Black	Phase V			
Red	Phase W			



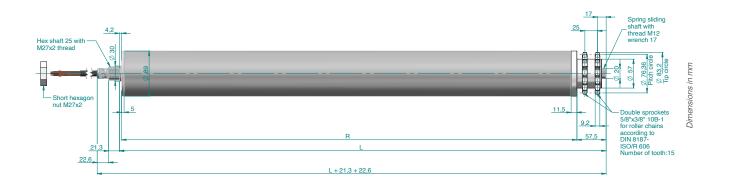
<sup>\*</sup>different length available on request

## **MOTOROLLER 89 DIMENSIONS - type 02**



R 898 mm L\* 960 mm Weight 22,4 Kg

## Motoroller 89 045 power back reference drawing 02



SIGNAL CABLE			
WIRE COLOR	FUNCTION		
Green	Hall U		
Yellow	Hall U/		
Gray	Hall V		
Pink	Hall V/		
White	Hall W		
Brown	Hall W/		
Red	+5VCC		
Blue	GND		
Drain Wire	shield		

POWER CABLE			
WIRE COLOR	FUNCTION		
White	Phase U		
Black	Phase V		
Red	Phase W		



<sup>\*</sup>different length available on request

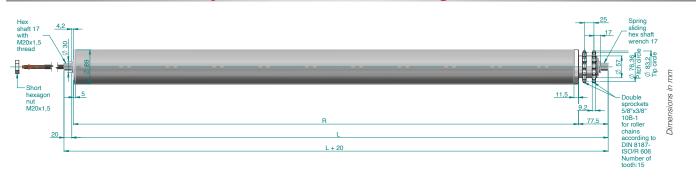
## **MOTOROLLER 89 DIMENSIONS - type 03**



### MTR 89 045 - TYPE 03

R 1320 mm L\* 1400 mm Weight 27 Kg

## Motoroller 89 045 power back reference drawing 03



SIGNAL CABLE			
WIRE COLOR	FUNCTION		
Green	Hall U		
Yellow	Hall U/		
Gray	Hall V		
Pink	Hall V/		
White	Hall W		
Brown	Hall W/		
Red	+5VCC		
Blue	GND		
Drain Wire	shield		

POWER CABLE				
WIRE COLOR	FUNCTION			
White	Phase U			
Black	Phase V			
Red	Phase W			

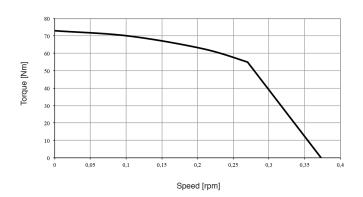


<sup>\*</sup>different length available on request

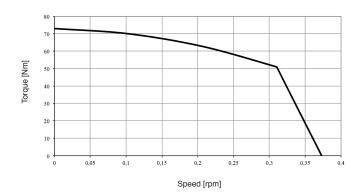
## **MOTOROLLER 89 045 TORQUE /SPEED CHARTS**



### **MOTOROLLER 89 045 04**



### **MOTOROLLER 89 045 15**



## **FEEDBACK FEATURES**

## H1 HALL SENSOR

Motor size		Motoroller 46 -60- 76
Nominal Voltage	V	5-9 ±5%
Nominal current	mA	100
Electronic type		OPEN COLLECTOR
N° of pulses revolution	ppr	84

## E1 INCREMENTAL ENCODER

Motor size		Motoroller 46 -60- 76
Nominal Voltage	Vdc	5-9 ±5%
Nominal current	mA	100
Electronic type		OPEN COLLECTOR
Zero impulse		ONE AT A LAP
N° of pulses revolution	ppr	896
Resolution	cpr	3584



# DMR SERVO DRIVES

The DMR series is a series of customized drives dedicated to logistic automation market.

The series features two models: DMR 50-5/50 and DMR76-10/65, designed and manufactured for driving gearless motorollers, exploiting its technological advantages based on direct drive without any gear for motion transmission.

## DMR 50-5/50 FEATURES

- > DUAL AXES OPERATION CAPABILITY
- > PERFECT MATCH WITH GEARLESS MOTOROLLER MTR46
- > I/O PROGRAMMABILITY
- > FUSE PROTECTION
- > CROSSBELT FUNCTIONALITY
- > CONVEYOR FUNCTIONALITY
- > SPEED AND ACCELERATION PROGRAMMABILITY

- > HALL SENSOR AND ENCODER FEEDBACK
- > DMR BROWSER SOFTWARE INTERFACE
- > RS 485 PROGRAMMING INTERFACE
- > CAN OPEN FIELDBUS
- > PHOTO EYE SUPPORT
- > 2 INPUT, 2 OUTPUT RELAY EACH AXIS





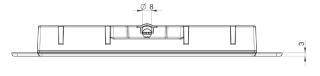
## *DMR 50-5/50 PRODUCT DATA*

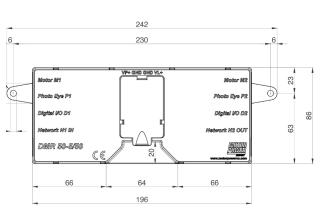
FEATURE	UNITS	DMR 50-5/50
Rated output power	W	180 each axis
Efficiency at rated power	%	>95
Operating supply voltage	Vdc	12-60
Typical supply voltage	Vdc	48
Maximum operating voltage	Vdc	80
Auxiliary supply voltage		24 V (8-30)
Rated output current	Arms	5
Peak output current	Arms	15
Peak time	s	3
PWM switching frequency	kHz	16 kHz
Maximum outputfrequency	Hz	<600
Commutation		Sinusoidal and space vector
Dimensions	WxDxH mm	196x70x27
Working temperature	°C	-20 ÷ +55
Storage temperature	°C	-40 ÷ +75
Humidity	%	85% not consdensing
Altitude without derating	m	1000
IP protection	IP	20



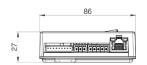
# SERVO DRIVE

## **DMR 50-5/50 PRODUCT DIMENSIONS**











## DMR 50-5/50 PRODUCT DATA

MOTOR CONNECTION	
PIN	NAME
1	Phase U
2	Phase V
3	Phase W
4	Thermal sensor
5	Power supply 5V
6	OV
7	Hall U/Inc A
8	Hall V/Inc B
9	Hall W/Inc Z

PHOTO EYE INPUT	
PIN	NAME
1	24V
2	GND
3	Photo eye input

POWER CONNECTION	
NAME	
24V logic	
0 V	
48 V power	

I/O DEFINITION		
PIN	DIRECTION	FUNCTION
1	Input	Enable
2	Input	Dir
3	Input	Analogf Input
4	Output	Fault
5	Output	Configurable

MOTOR

# **DMR SERVO DRIVES**

DMR 76-10/65 HP is a digital drive for motorollers in cross belt applications. Main features of this drive are current digital control achieved with the technique of vector space and updated with a 10 kHz frequency. Speed digital loop with proportional-integral compensator updated with 10 kHz frequency. Position digital loop with proportional compensator and handling of dead zone updated with 10 kHz frequency. Digital Profibus interface for connecting to supervisor PLC. Motor feedback interface via Hall sensors.

### **DMR 76-10/65 FEATURES**

- > THE PERFECT MATCHED DRIVE FOR GEARLESS MOTOROLLER MTR76
- > USB PROGRAMMING INTERFACE
- > PROFIBUS FIELBUS DP V1
- > I/O PROGRAMMABILITY
- > I/O PROXY DUAL LOOP

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- > DMR BROWSER SOFTWARE INTERFACE
- > FUSE PROTECTION
- > CROSSBELT FUNCTIONALITY
- > SPEED AND ACCELERATION PROGRAMMABILITY
- > HALL SENSOR AND ENCODER FEEDBACK
- > 2 INPUT, 2 OUTPUT RELAY



## DMR 76-10/65 PRODUCT DATA

FEATURE	UNITS	DMR 76-10/65
Rated output power	W	650
Efficiency at rated power	%	>95
Operating supply voltage	Vdc	24-80
Typical supply voltage	Vdc	48-65
Maximum operating voltage	Vdc	85
Auxiliary supply voltage		-
Rated output current	Arms	10
Peak output current	Arms	50
Peak time	s	0,75 on 20s
PWM switching frequency	kHz	16 kHz
Maximum outputfrequency	Hz	<600
Commutation		Sinusoidal and space vector
Dimensions	WxDxH mm	250x150x45
Working temperature	°C	-20 ÷ +55
Storage temperature	°C	-40 ÷ +75
Humidity	%	85% not consdensing
Altitude without derating	m	1000
IP protection	IP	54 on drive front 40 on the whole drive

SEE IT BEFORE IT HAPPENS



# **DMR 76-10/65**

## DMR 76-10/65 PRODUCT DATA

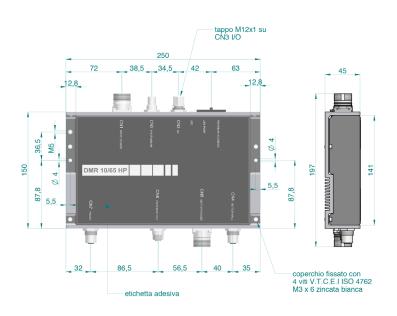
## HARDWARE AND FIRMWARE CHARACTERISTICS

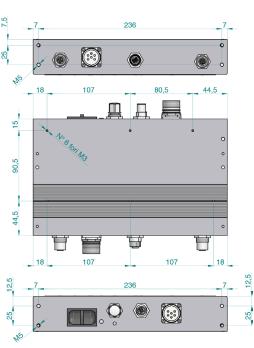
- > ONE ELECTRONIC BOARD FOR CONTROL LOGIC AND POWER
- > ONE SUPPLY FOR ELECTRONIC CONTROL AND MOTOR OUTPUT STAGE
- > PROFIBUS SLAVE COMMAND INTERFACE WITH DIP SWITCH NODE ADDRESS SELECTION
- > USB DEVICE INTERFACE FOR CONFIGURATION AND MAINTENANCE
- > CONTROL THROUGH SINUSOISAL ALGORITHM AND HALL SENSOR FEEDBACK
- > GENERIC I/O PROGRAMMABILITY
- > I/O PROXI PROGRAMMABILITY

## INTERFACE

> THIS DRIVE IS EQUIPPED WITH SOFTWARE USER INTERFACE
"DMR BROWSER" FOR OPERATING, MONITORING AND SUPERVISION
OF THE APPLICATION. REFER TO THE APPROPRIATE MANUAL FOR
INSTALLATION INSTRUCTIONS AND USE.

## **PRODUCT DIMENSIONS**







# DMR 76-10/65

## **CONNECTION**

DRIVE POWER		
PIN	NAME	
1	V+	
2	-	
3	-	
4	-	
5	V-	
6	-	

PROFIBUS IN	
PIN	NAME
1	-
2	DATA-/A-LINE
3	-
4	-
5	DATA+/B-LINE

PROFIBUS OUT	
PIN	NAME
1	V+
2	DATA-/A-LINE
3	$V_{_{ m REF}}$
4	DATA+/B-LINE
5	-

DIGITAL I/O	
PIN	NAME
1	OUT1 COM
2	INRET 123
3	+24V <sub>DC</sub>
4	OUT1 NC
5	IN1
6	IN2
7	IN3
8	GND (+24 V <sub>DC</sub> )



# SERVO DRIVE

## **CONNECTION**

MOTOR OUTPUT		
PIN	NAME	
1	-	
2	U	
3	V	
4	W	
5	-	
6	PE	

FEEDBACK		
PIN	NAME	
1	U/A	
2	V/B	
3	W/Z	
4	5V <sub>DC</sub>	
5	GND	

PROXY DUAL LOOP		
PIN	NAME	
1	+24V <sub>DC</sub> PROXY	
2	INRET 123 PROXY	
3	GND (+24V <sub>DC</sub> )	
4	OUT2 NO	
5	OUT2 NO	
6	IN7 PROXY	
7	+24 V <sub>DC</sub>	
8	OUT2 COM	





## SERVO DRIVE

The LITE PRO series is represented by the extremely compact 4-quadrants drives perfect matched to control motoroller 60. This series features as standard CanOpen interface and a complete programmable version with integral Motion Process Unit, that allows stand alone and network architecture operation.

## **FEATURES**

- > STANDARD FEEDBACK TTL ENCODER AND HALL SENSOR
- > DIGITAL I/O: UP TO 8 DIGITAL INPUTS AND 1 OR 2 DIGITAL OUTPUTS CUSTOMIZIBLE WITH SEVERAL BUILT-IN FUNCTIONS
- > CONTROL: STANDARD PI CONTROL LOOP
- > SERVO MODES: TORQUE, VELOCITY AND POSITION WITH S-CURVE PROFILE
- > INTERNAL SCRIPT
- > EXTREME COMPACT DESIGN
- > USB PROGRAMMING KEY

## INTERFACE

- > ANALOG VELOCITY AND TORQUE COMMAND ± 10V
- > CANopen





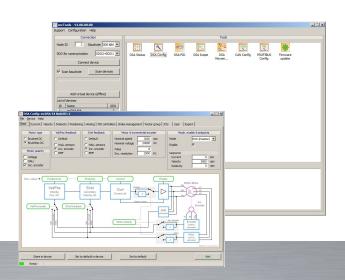
# COMPACT AND PROFITABLE

## PRODUCT DATA

FEATURE	UNITS	LPRO E40
Input voltage	VDC	48
Efficiency at rated power	%	>95
Auxiliary supply voltage	VDC	9 30
Continuous current	Arms	8
Peak current	Arms	24
Ambient operating temperature	°C	0 to + 40°
Maximum humidity	%	5÷85% not condensing
Mounting method		Wall mounting DIN Rail
Dimensions	LxWxH mm	110x22,5x77
Weight	gr	110
Digital IN		4
Digital OUT		1

## LITE PRO USER INTERFACE

- > EASY AND INTUITIVE PC SOFTWARE ALLOWS A FAST PARAMETERIZATION OF THE LITE PRO
- > SIMPLE SCOPE
- > SCRIPT EDITING





motorpowerco.com

**MOTION CONTROL** 

**MECHATRONICS** 



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